

MODELLING AND SIMULATION OF LIQUID-VAPOR PHASE TRANSITION

A Boiling Crisis Study Contribution

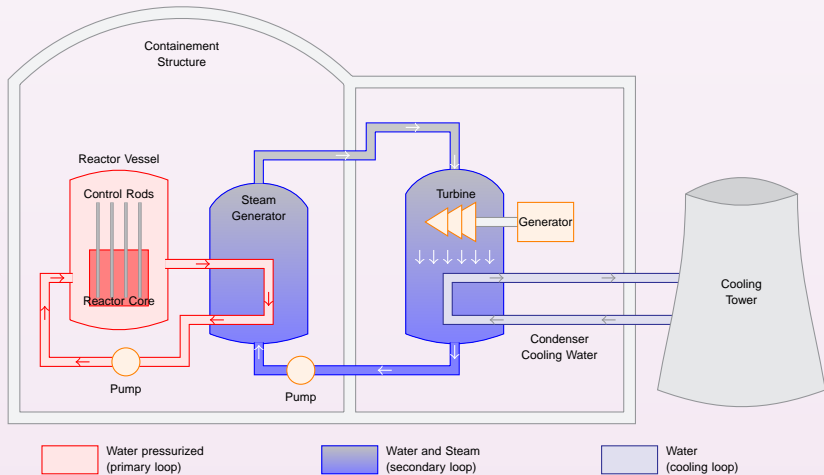
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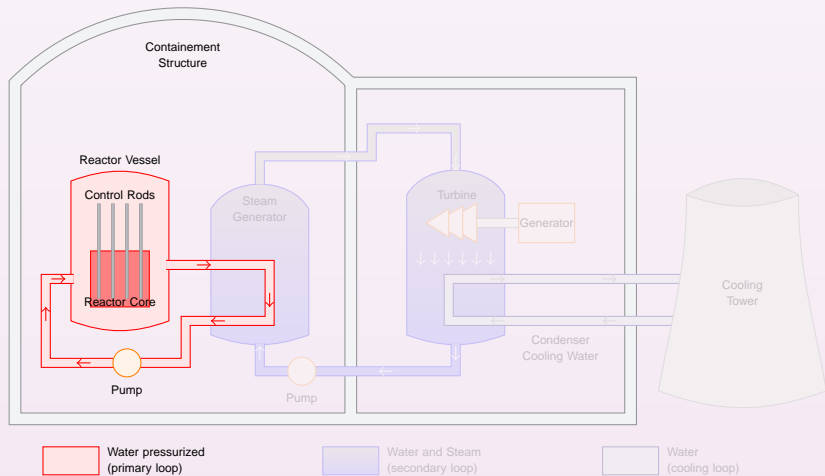
²CEA Saclay - SFME/LETR



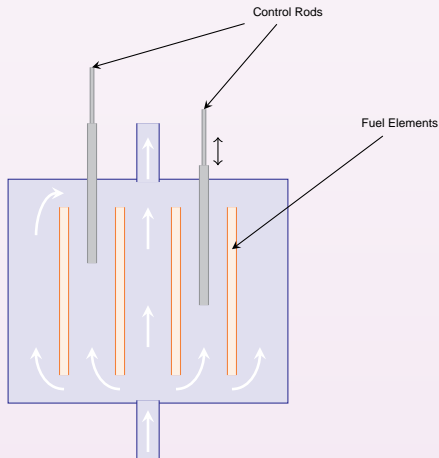
PRESSURIZED WATER REACTOR



PRESSURIZED WATER REACTOR



CORE OF A PRESSURIZED WATER REACTOR

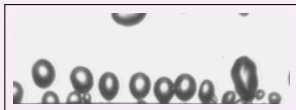


BOILING CRISIS

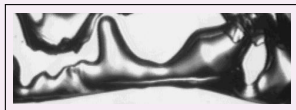
PHENOMENON

Liquid phase heated by a wall at a fixed temperature T^{wall} (pool boiling).
When T^{wall} increases, we switch from a **nucleate boiling** to a **film boiling**.

Nucleate Boiling



Film Boiling



source: http://www.spaceflight.esa.int/users/fluids/TT_boiling.htm

OUTLINE

- 1 Model
- 2 Numerical Method
- 3 Numerical Tests
- 4 Conclusion

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EULER SYSTEM

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0, \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + P \mathbb{I}) = \mathfrak{V}_{\text{vf}} - \mathfrak{S}_{\text{sf}}, \\ \partial_t\left(\rho\left(\frac{|\mathbf{u}|^2}{2} + \varepsilon\right)\right) + \operatorname{div}\left(\rho\left(\frac{|\mathbf{u}|^2}{2} + \varepsilon\right)\mathbf{u} + P \mathbf{u}\right) = (\mathfrak{V}_{\text{vf}} - \mathfrak{S}_{\text{sf}}) \cdot \mathbf{u} - \operatorname{div}(\mathbf{q}). \end{cases}$$

- $(\mathbf{x}, t) \mapsto \rho$ specific density,
- $(\mathbf{x}, t) \mapsto \varepsilon$ specific internal energy,
- $(\mathbf{x}, t) \mapsto \mathbf{u}$ velocity;
- $(\rho, \varepsilon) \mapsto \mathfrak{V}_{\text{vf}}$ volumic forces,
- $(\rho, \varepsilon) \mapsto \mathfrak{S}_{\text{sf}}$ surface forces,
- $(\rho, \varepsilon) \mapsto \operatorname{div}(\mathbf{q})$ heat transfert.

$(\rho, \varepsilon) \mapsto P$ pressure law.

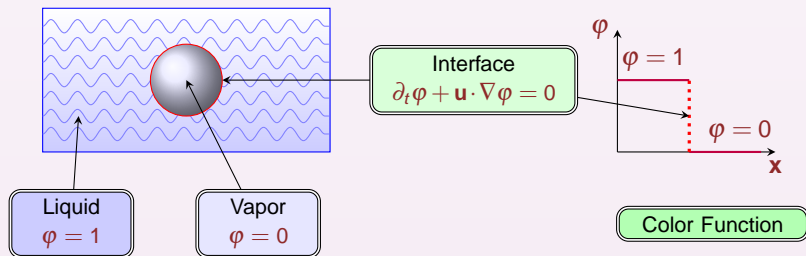
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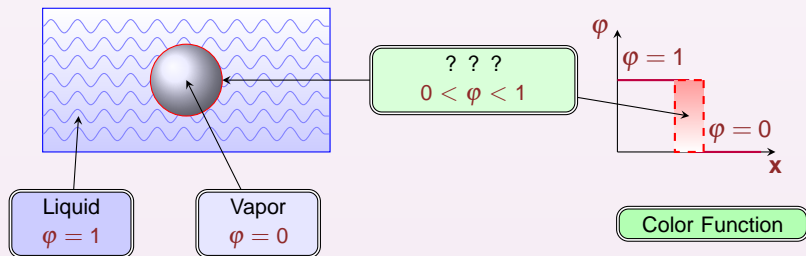
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LIQUID-VAPOR INTERFACE



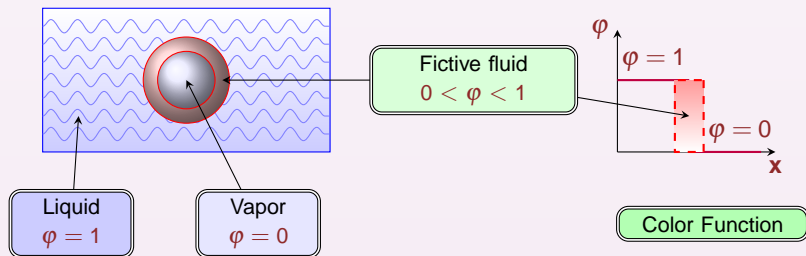
$$(\rho, \varepsilon) \mapsto P = \begin{cases} P^{\text{liq}} & \text{if } \varphi = 1; \\ P^{\text{vap}} & \text{if } \varphi = 0. \end{cases}$$

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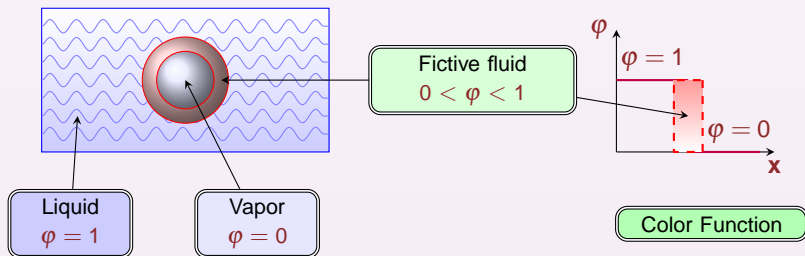
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LIQUID-VAPOR INTERFACE



➔ Goal: define a global pressure law such that

- $(\rho, \varepsilon, \mathbf{u}, P)$ are continuous (3 zones)
- the interface position and the phase change are implicit (\leadsto ~~φ~~)
- coherence with classical thermodynamics [H. Callen]

EOS OF EACH PHASE $\alpha = 1, 2$

$$\left. \begin{array}{l} \tau_\alpha \text{ specific volume} \\ \varepsilon_\alpha \text{ specific internal energy} \end{array} \right\} \Rightarrow \mathbf{w}_\alpha \stackrel{\text{def}}{=} (\tau_\alpha, \varepsilon_\alpha);$$

$\mathbf{w}_\alpha \mapsto s_\alpha$ specific entropy (Hessian matrix neg. def.);

$$\left. \begin{array}{l} \left. \begin{array}{l} T_\alpha \stackrel{\text{def}}{=} \left(\frac{\partial s_\alpha}{\partial \varepsilon_\alpha} \Big|_{\tau_\alpha} \right)^{-1} > 0 \\ P_\alpha \stackrel{\text{def}}{=} T_\alpha \frac{\partial s_\alpha}{\partial \tau_\alpha} \Big|_{\varepsilon_\alpha} > 0 \\ g_\alpha \stackrel{\text{def}}{=} \varepsilon_\alpha + P_\alpha \tau_\alpha - T_\alpha s_\alpha \end{array} \right\} \begin{array}{l} \text{temperature,} \\ \text{pressure,} \\ \text{free enthalpy (Gibbs potential).} \end{array} \end{array} \right\}$$

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EOS WITHOUT PHASE CHANGE

- $\mathbf{w} \stackrel{\text{def}}{=} y\mathbf{w}_1 + (1 - y)\mathbf{w}_2;$
- y mass fraction;
- z volume fraction s.t. $y\tau_1 = z\tau;$
- ψ energy fraction s.t. $y\varepsilon_1 = \psi\varepsilon.$

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ENTROPY WITHOUT PHASE CHANGE

$$\sigma \stackrel{\text{def}}{=} y s_1(\mathbf{w}_1) + (1-y) s_2(\mathbf{w}_2) = y s_1\left(\frac{z}{y}\tau, \frac{\psi}{y}\varepsilon\right) + (1-y) s_2\left(\frac{1-z}{1-y}\tau, \frac{1-\psi}{1-y}\varepsilon\right)$$

$$P = \left(\frac{\partial \sigma}{\partial \varepsilon} \Big|_{\tau, y, z, \psi} \right)^{-1} \frac{\partial \sigma}{\partial \tau} \Big|_{\varepsilon, y, z, \psi}$$

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EOS WITH PHASE CHANGE

ENTROPY WITHOUT PH.CH.

$$(\mathbf{w}, z, y, \psi) \mapsto \sigma$$



ENTROPY AT EQUILIBRIUM

$$\mathbf{w} \mapsto s^{\text{eq}}$$

DEFINITION [H. CALLEN, PH. HELLUY ...]

Optimization Problem:

$$s^{\text{eq}}(\mathbf{w}) \stackrel{\text{def}}{=} \max_{z, y, \psi \in [0, 1]^3} \sigma(\mathbf{w}, z, y, \psi)$$

Optimality Condition:

$$\begin{cases} T_1(z, y, \psi) = T_2(z, y, \psi) \\ P_1(z, y, \psi) = P_2(z, y, \psi) \\ g_1(z, y, \psi) = g_2(z, y, \psi) \\ z, y, \psi \in]0, 1[^3 \end{cases}$$

Solution: (z^*, y^*, ψ^*)

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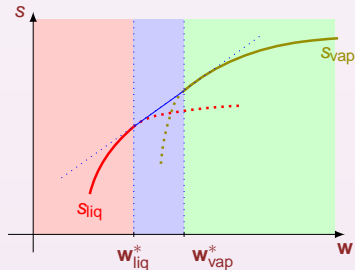
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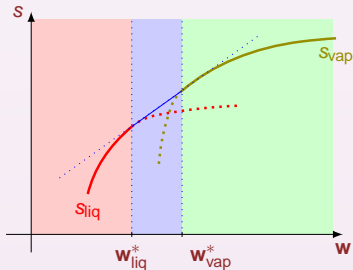
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EOS WITH PHASE CHANGE

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ENTROPY AT EQUILIBRIUM

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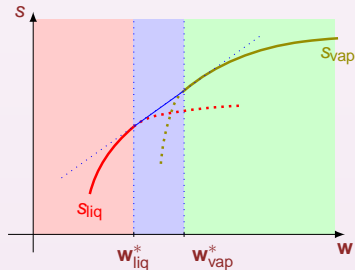
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FROM $\mathbf{w} \mapsto \mathbf{s}^{\text{eq}}$ TO $\mathbf{w} \mapsto P^{\text{eq}}$

For all $\tilde{\mathbf{w}}$ fixed, we seek $(\mathbf{w}_{\text{liq}}^*, \mathbf{w}_{\text{vap}}^*, y^*)$ as the solution of the system

$$\begin{cases} P_{\text{liq}}(\mathbf{w}_{\text{liq}}) = P_{\text{vap}}(\mathbf{w}_{\text{vap}}) \\ T_{\text{liq}}(\mathbf{w}_{\text{liq}}) = T_{\text{vap}}(\mathbf{w}_{\text{vap}}) \\ g_{\text{liq}}(\mathbf{w}_{\text{liq}}) = g_{\text{vap}}(\mathbf{w}_{\text{vap}}) \\ \tilde{\mathbf{w}} = y\mathbf{w}_{\text{liq}} + (1-y)\mathbf{w}_{\text{vap}} \end{cases}$$

- 1 if $y^* \in]0, 1[$ then $\tilde{\mathbf{w}}$ is an equilibrium mixture state

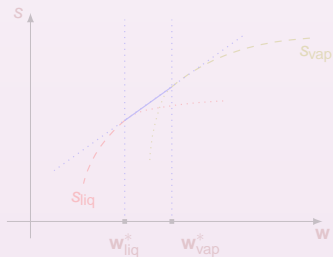
$$s^{\text{eq}}(\tilde{\mathbf{w}}) = y^* s_{\text{liq}}(\mathbf{w}_{\text{liq}}^*) + (1-y^*) s_{\text{vap}}(\mathbf{w}_{\text{vap}}^*);$$

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- 2 if the system has no solution or $y^* \notin]0, 1[$ then $\tilde{\mathbf{w}}$ is a monophasique pure state

$$s^{\text{eq}}(\tilde{\mathbf{w}}) = \max\{s_{\text{liq}}(\tilde{\mathbf{w}}), s_{\text{vap}}(\tilde{\mathbf{w}})\},$$

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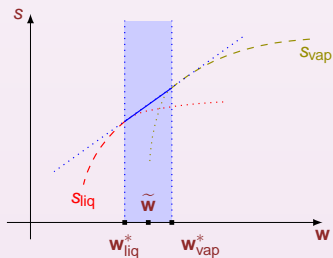
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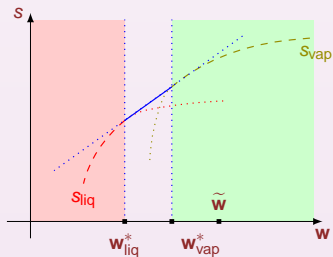
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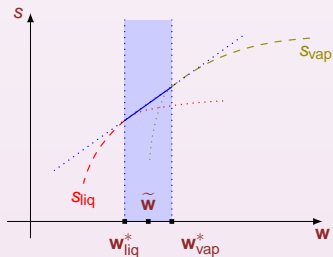
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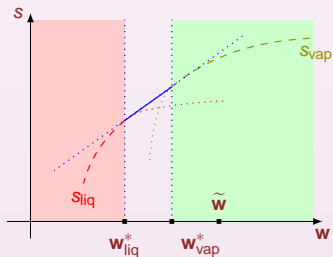
$$s^{\text{eq}}(\tilde{\mathbf{w}}) = y^* s_{\text{liq}}(\mathbf{w}_{\text{liq}}^*) + (1-y^*) s_{\text{vap}}(\mathbf{w}_{\text{vap}}^*),$$

$$P^{\text{eq}}(\tilde{\mathbf{w}}) = P_{\text{liq}}(\mathbf{w}_{\text{liq}}^*) = P_{\text{vap}}(\mathbf{w}_{\text{vap}}^*);$$

- 2 if the system has no solution or $y^* \notin]0, 1[$ then $\tilde{\mathbf{w}}$ is a **monophasique pure state**

$$s^{\text{eq}}(\tilde{\mathbf{w}}) = \max\{s_{\text{liq}}(\tilde{\mathbf{w}}), s_{\text{vap}}(\tilde{\mathbf{w}})\},$$

$$P^{\text{eq}}(\tilde{\mathbf{w}}) = P_{\alpha}(\tilde{\mathbf{w}}).$$



DYNAMIC LIQUID-VAPOR PHASE CHANGE

EULER SYSTEM

$$\begin{cases} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = 0, \\ \partial_t(\rho \mathbf{u}) + \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u} + P^{\text{eq}} \mathbb{I}) = 0 \\ \partial_t \left(\rho \left(\frac{|\mathbf{u}|^2}{2} + \varepsilon \right) \right) + \operatorname{div} \left(\rho \left(\frac{|\mathbf{u}|^2}{2} + \varepsilon \right) \mathbf{u} + P^{\text{eq}} \mathbf{u} \right) = 0 \end{cases} \quad \text{with } P^{\text{eq}} \stackrel{\text{def}}{=} \frac{S_\tau^{\text{eq}}}{S_\varepsilon^{\text{eq}}}.$$

PROPERTIES [G. ALLAIRE, G. FACCANONI, S. KOKH]

If $\tau_1^* \neq \tau_2^*$ and $\varepsilon_1^* \neq \varepsilon_2^*$ (first order phase transition) then

$$\textcircled{1} c(w) > 0, \quad \textcircled{2} s_{\tau\varepsilon}^{\text{eq}}(w) > 0$$

- ① Euler system: strict hyperbolicity (\neq p-system),
- ② Riemann problem: multitude of entropic (Lax) solutions [R. Menikoff, B. J. Plohr], uniqueness of Liu solution.

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OUTLINE

- 1 Model
- 2 Numerical Method**
- 3 Numerical Tests
- 4 Conclusion

HOW TO SIMULATE THE LIU SOLUTION

- Exact Riemann Solver [A. Voß]
- Viscuous Solver (the Liu solution is the only solution that has a viscuous profile) [S. Jaouen]
- Solver(s) based on **Relaxation Approach** [F. Coquel, B. Perthame], [Th. Barberon, Ph. Helluy], [Ph. Helluy, N. Seguin], [F. Coquel, F. Caro, D. Jamet, S. Kokh], ...

RELAXATION APPROACH

$$\partial_t \mathbf{U} + \operatorname{div} \mathbf{F}(\mathbf{U}) = \mathbf{0}$$

RELAXATION APPROACH

$$\partial_t \mathbf{V} + \operatorname{div} \mathbf{G}(\mathbf{V}) = \frac{1}{\mu} \mathbf{R}(\mathbf{V}) \quad \xrightarrow[\mu \rightarrow 0]{\text{Formally}} \quad \partial_t \mathbf{U} + \operatorname{div} \mathbf{F}(\mathbf{U}) = \mathbf{0}$$

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Formally
 $\mu_j \rightarrow 0$

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REMARK: ~~$\partial_t \psi + \mathbf{u} \cdot \operatorname{grad} \psi = 0$~~ $\rightsquigarrow T_1 = T_2$.

NUMERICAL SCHEME

$$\partial_t \mathbf{V} + \text{div} \mathbf{G}(\mathbf{V}) = \mathbf{S}(\mathbf{V}) + \frac{1}{\mu} \mathbf{R}(\mathbf{V})$$

 \mathbf{V}_i^n

$\ominus \mu_j = +\infty$



$\partial_t \mathbf{V} + \text{div} \mathbf{G}(\mathbf{V}) = \mathbf{S}(\mathbf{V})$

Aug. System: 5-eq. iso-T
 Num. Scheme: op. splitting
 Conv.: [G. Allaire and all.]
 Surf. Tens.: [J. U. Brackbill and all.]
 Heat: 2D implicit

 \mathbf{V}_i^{n+1}

$\oplus \mu_j = 0$



$\mathbf{R}(\mathbf{V}) = \mathbf{0}$

update fractions
 (y, z, ψ) by
 projecting $\mathbf{V}_i^{n+1/2}$
 onto the
 P, T, g equilibrium

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$$\textcircled{2} \mu_j = 0$$



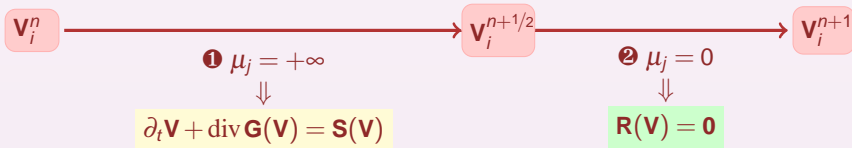
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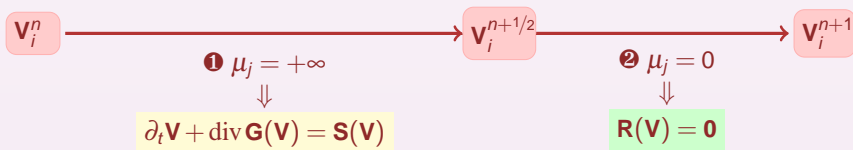


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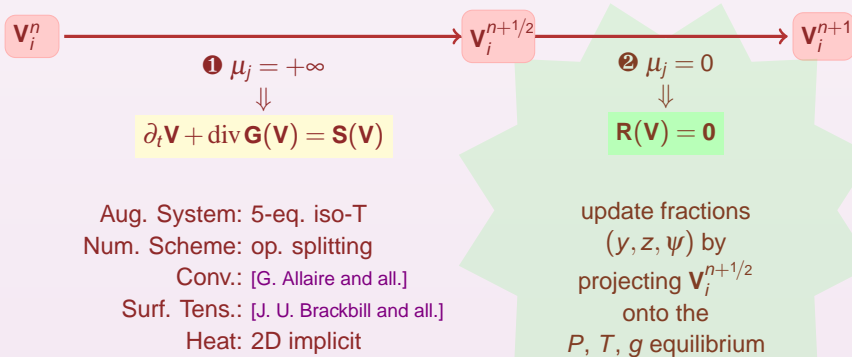


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ANALYTICAL EOS

▶▶ Water Example

 (τ, ε) fixed $(\tau_1, \varepsilon_1, \tau_2, \varepsilon_2, y)$ SOLUTION OF

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least square
approximation

$$T \mapsto P = \hat{P}^{\text{sat}}(T) \approx P^{\text{sat}}(T)$$

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TABULATED EOS

» Water Examples

(τ, ε) fixed

T SOLUTION OF

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}}

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TABULATED EOS

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$$\frac{\tau - \tau_2^{\text{sat}}(T)}{\tau_1^{\text{sat}}(T) - \tau_2^{\text{sat}}(T)} = \frac{\varepsilon - \varepsilon_2^{\text{sat}}(T)}{\varepsilon_1^{\text{sat}}(T) - \varepsilon_2^{\text{sat}}(T)}$$

with $\begin{pmatrix} \tau \\ \varepsilon \end{pmatrix}_{\alpha}^{\text{sat}}(T)$ tabulated

$$\frac{\tau - \widehat{\tau}_2^{\text{sat}}(T)}{\widehat{\tau}_1^{\text{sat}}(T) - \widehat{\tau}_2^{\text{sat}}(T)} = \frac{\varepsilon - \widehat{\varepsilon}_2^{\text{sat}}(T)}{\widehat{\varepsilon}_1^{\text{sat}}(T) - \widehat{\varepsilon}_2^{\text{sat}}(T)}$$

with $\begin{pmatrix} \widehat{\tau} \\ \widehat{\varepsilon} \end{pmatrix}_{\alpha}^{\text{sat}}(T)$

}}

least square approximations

TABULATED EOS

» Water Examples

(τ, ε) fixed

T SOLUTION OF

$$\frac{\tau - \tau_2^{\text{sat}}(T)}{\tau_1^{\text{sat}}(T) - \tau_2^{\text{sat}}(T)} = \frac{\varepsilon - \varepsilon_2^{\text{sat}}(T)}{\varepsilon_1^{\text{sat}}(T) - \varepsilon_2^{\text{sat}}(T)}$$

with $\begin{pmatrix} \tau \\ \varepsilon \end{pmatrix}_{\alpha}^{\text{sat}}(T)$ tabulated

$$\frac{\tau - \widehat{\tau}_2^{\text{sat}}(T)}{\widehat{\tau}_1^{\text{sat}}(T) - \widehat{\tau}_2^{\text{sat}}(T)} = \frac{\varepsilon - \widehat{\varepsilon}_2^{\text{sat}}(T)}{\widehat{\varepsilon}_1^{\text{sat}}(T) - \widehat{\varepsilon}_2^{\text{sat}}(T)}$$

with $\begin{pmatrix} \widehat{\tau} \\ \widehat{\varepsilon} \end{pmatrix}_{\alpha}^{\text{sat}}(T)$

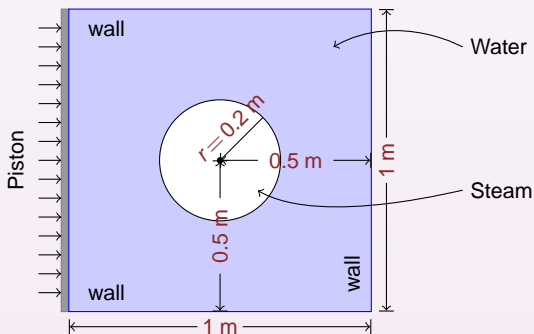
}}

least square approximations

OUTLINE

- 1 Model
- 2 Numerical Method
- 3 Numerical Tests**
- 4 Conclusion

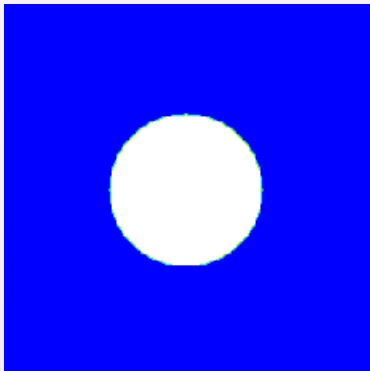
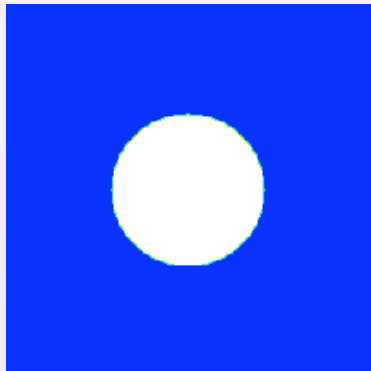
COMPRESSION OF A VAPOR BUBBLE



Compression of a 2D Vapor Bubble involving two Stiffened Gases for water and steam.

The piston moves towards right at constant speed $u_p = 30$ m/s.

COMPRESSION OF A VAPOR BUBBLE

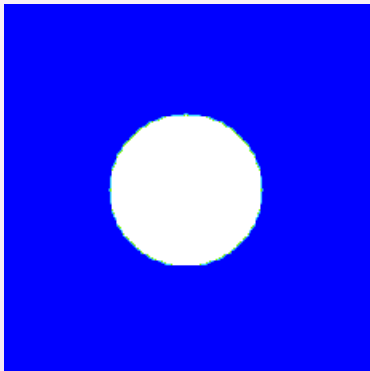
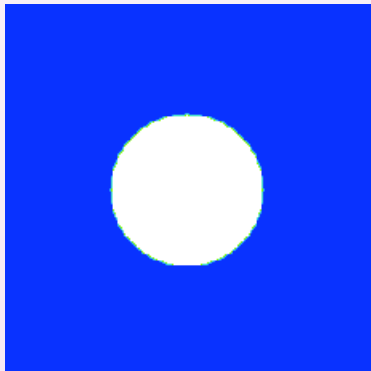
Mass Fraction y Density ρ  $t = 0.00$ ms

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

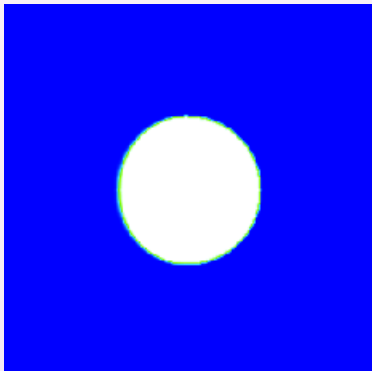
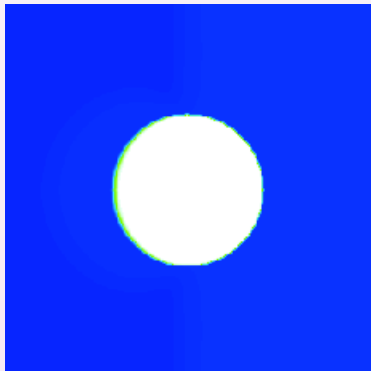
Mass Fraction y Density ρ  $t = 0.00$ ms

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

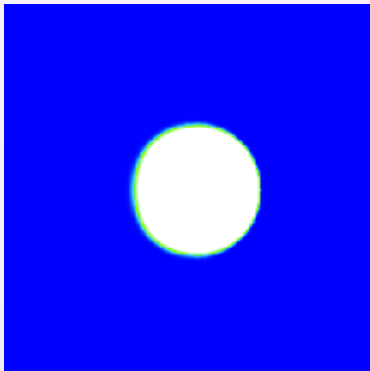
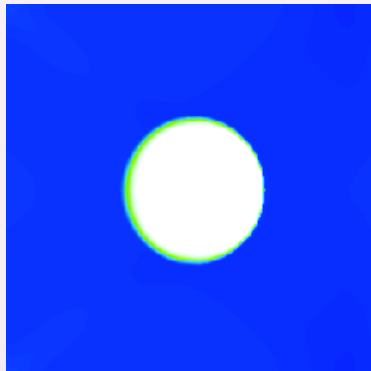
Mass Fraction y Density ρ  $t = 0.89 \text{ ms}$

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

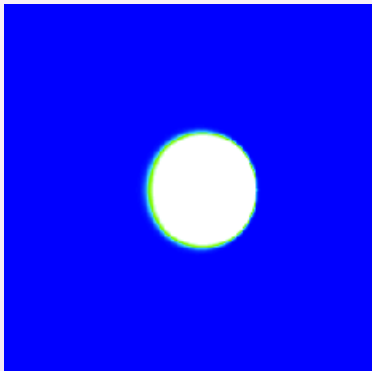
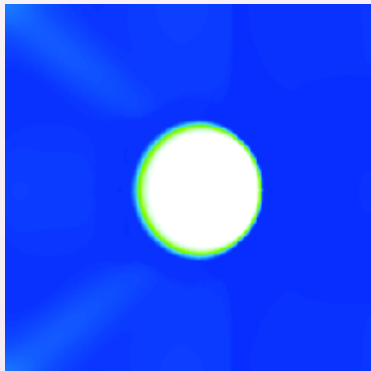
Mass Fraction y Density ρ  $t = 1.09 \text{ ms}$

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y Density ρ  $t = 1.49 \text{ ms}$

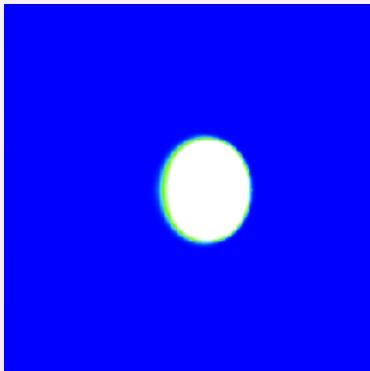
◀ Geometry

▶ Play

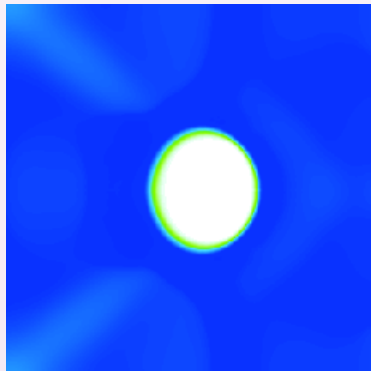
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



$t = 1.80$ ms

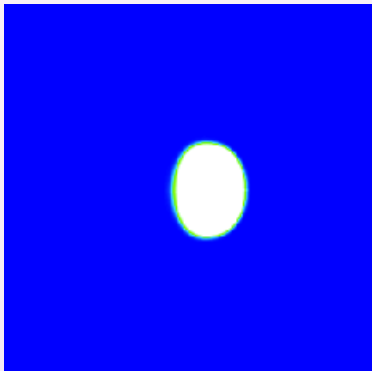
◀ Geometry

▶ Play

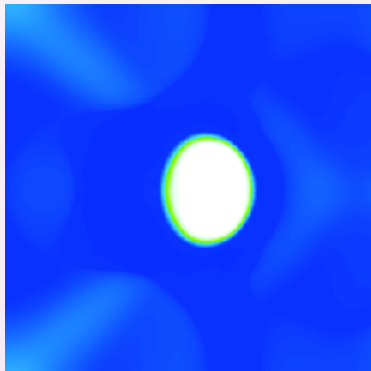
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



$t = 2.09$ ms

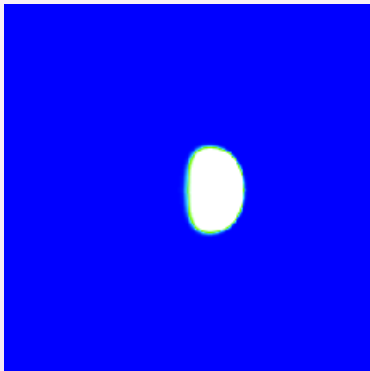
◀ Geometry

▶ Play

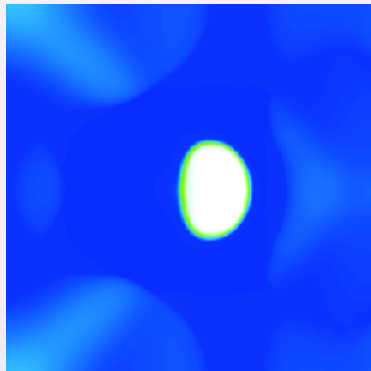
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



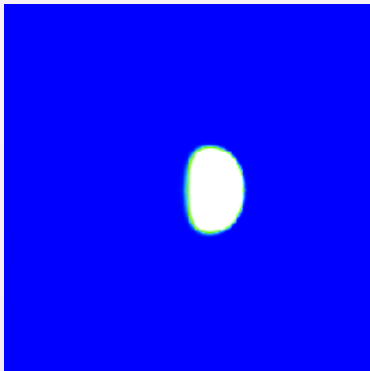
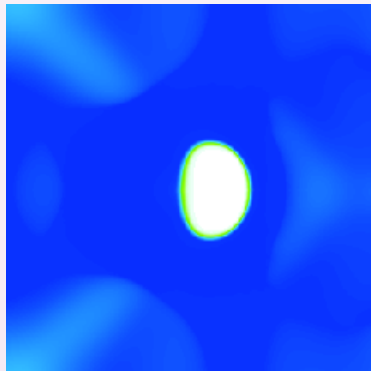
$t = 2.39$ ms

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y Density ρ  $t = 2.69 \text{ ms}$

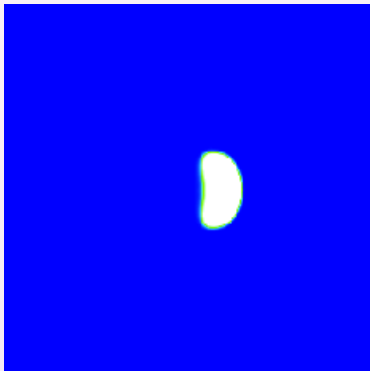
◀ Geometry

▶ Play

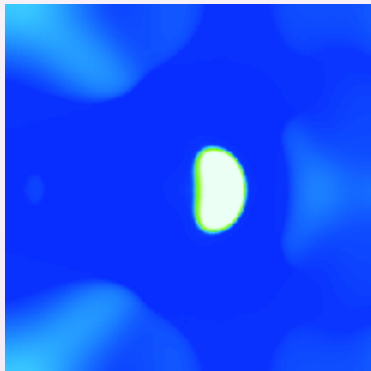
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



$t = 2.99$ ms

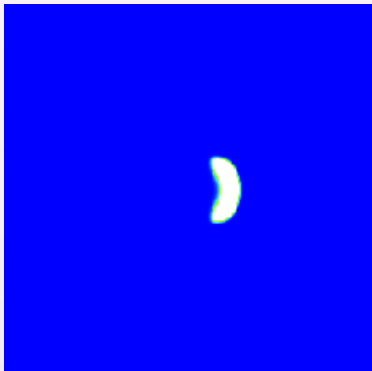
◀ Geometry

▶ Play

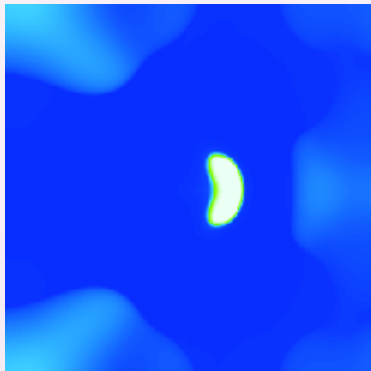
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



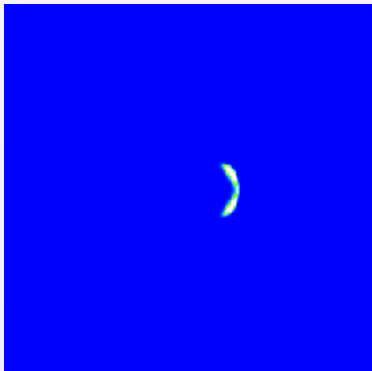
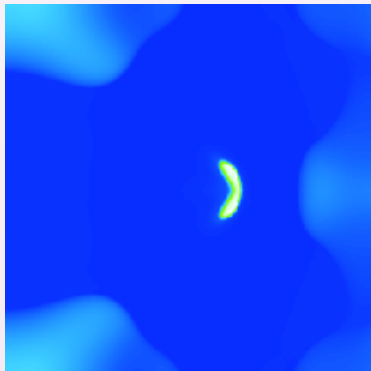
$t = 3.29$ ms

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y Density ρ  $t = 3.49 \text{ ms}$

◀ Geometry

▶ Play

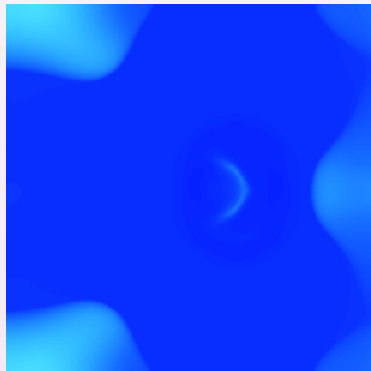
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



$t = 3.60$ ms

◀ Geometry

▶ Play

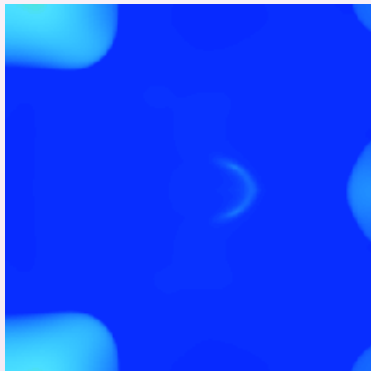
▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

Mass Fraction y



Density ρ



$t = 3.80$ ms

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

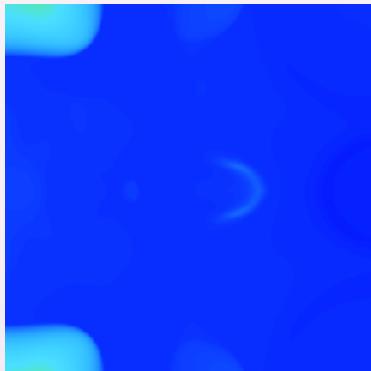
Mass Fraction y Density ρ  $t = 3.99 \text{ ms}$

◀ Geometry

▶ Play

▶▶ Skip

COMPRESSION OF A VAPOR BUBBLE

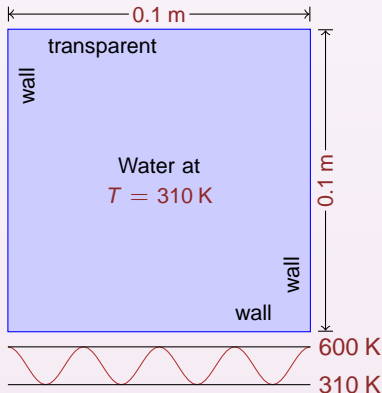
Mass Fraction y Density ρ  $t = 4.10$ ms

◀ Geometry

▶ Play

▶▶ Skip

NUCLEATING BUBBLES

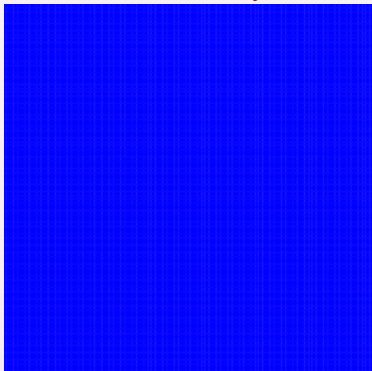


Nucleation of a 2D Vapor Bubbles involving two Stiffened Gases for water and steam. The temperature of the south wall is fixed at

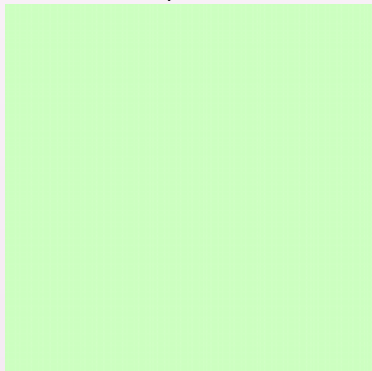
$$T^{\text{wall}} = 310 + (600 - 310)(1 + \cos(6\pi x))/2.$$

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



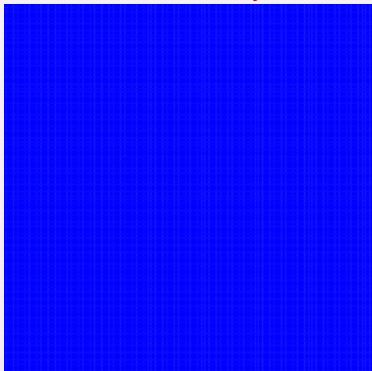
◀ Geometry

▶ Play

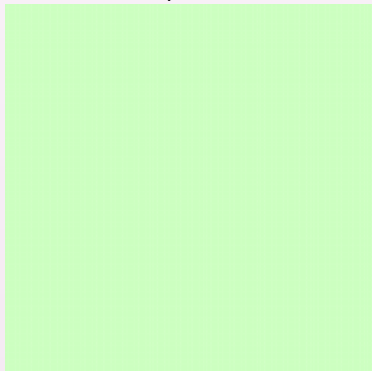
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



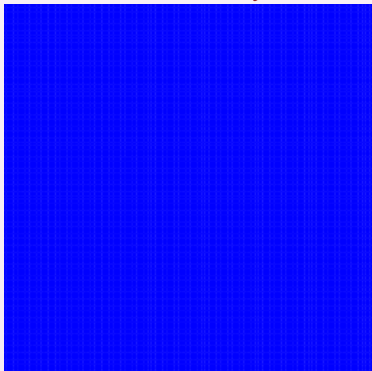
◀ Geometry

▶ Play

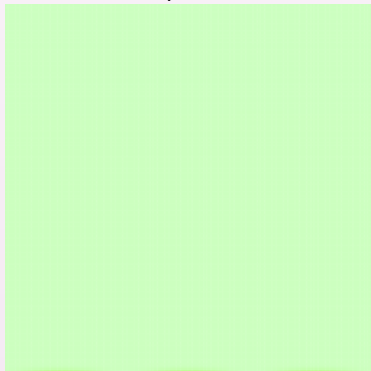
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



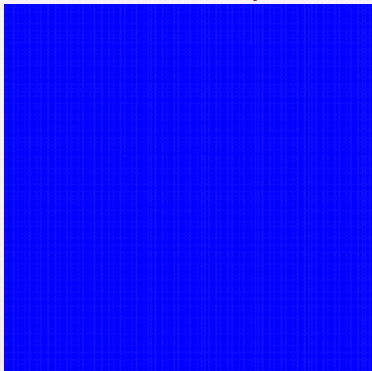
◀ Geometry

▶ Play

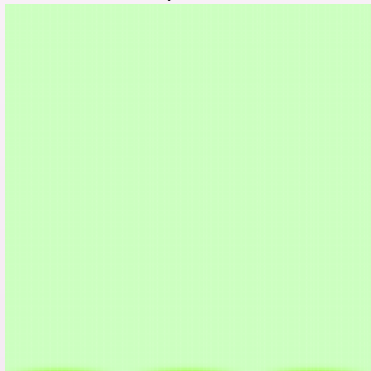
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



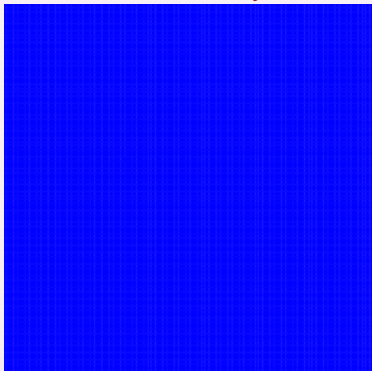
◀ Geometry

▶ Play

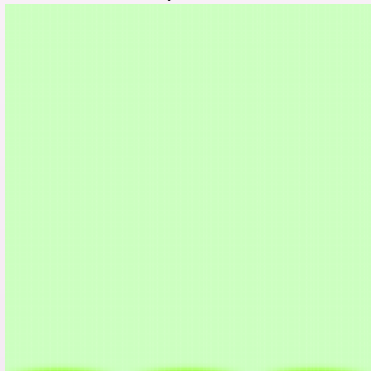
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



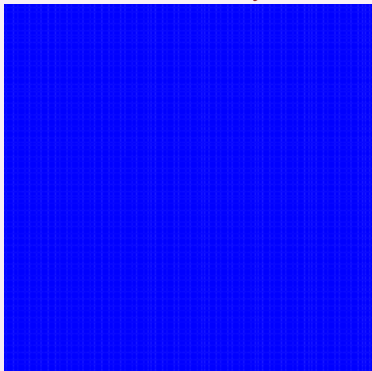
◀ Geometry

▶ Play

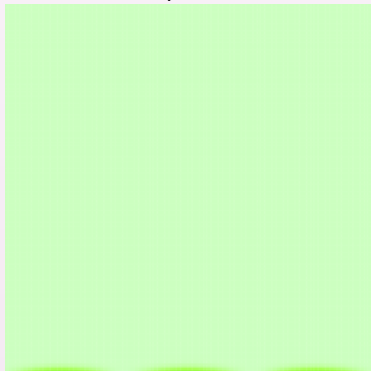
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



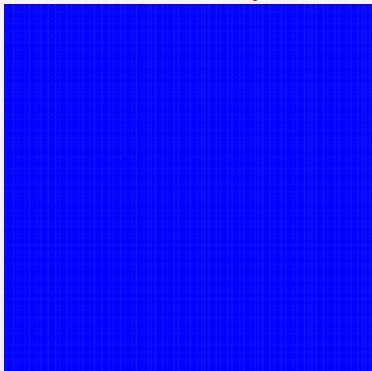
◀ Geometry

▶ Play

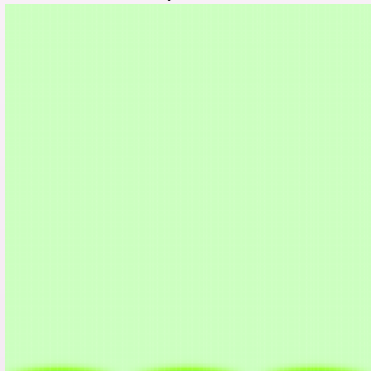
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



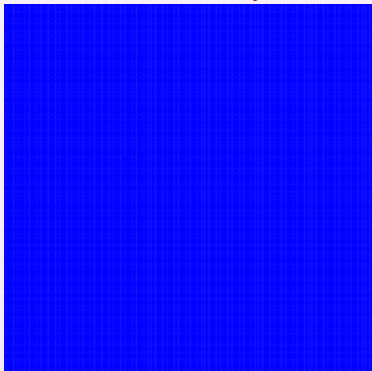
◀ Geometry

▶ Play

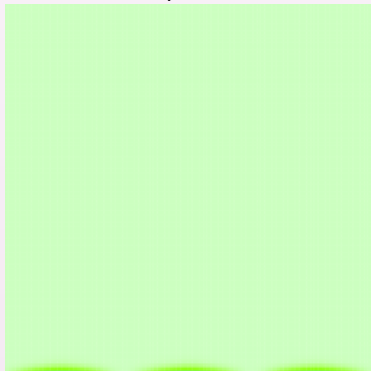
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



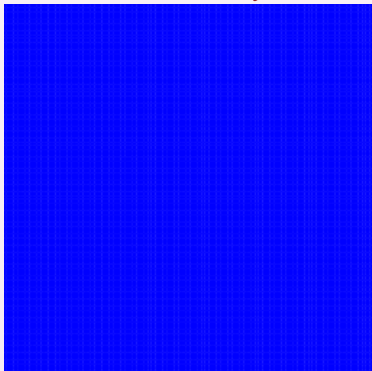
◀ Geometry

▶ Play

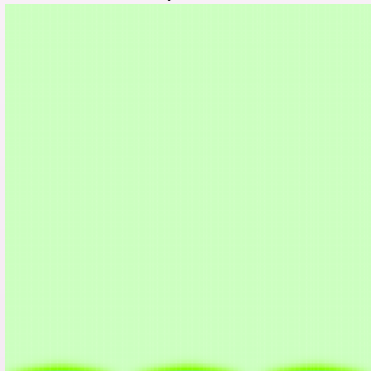
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



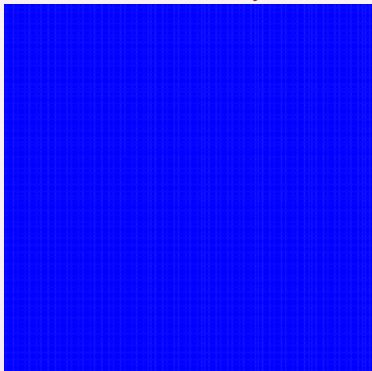
◀ Geometry

▶ Play

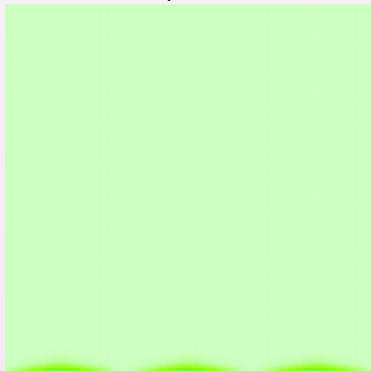
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



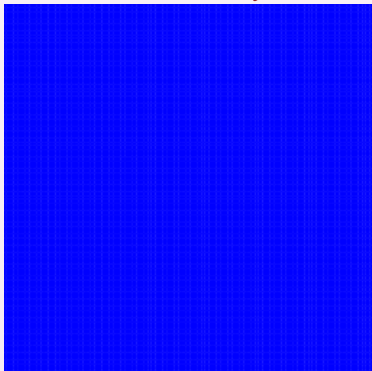
◀ Geometry

▶ Play

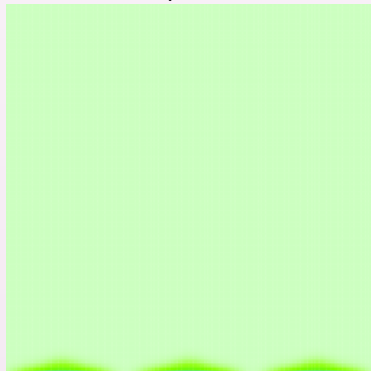
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



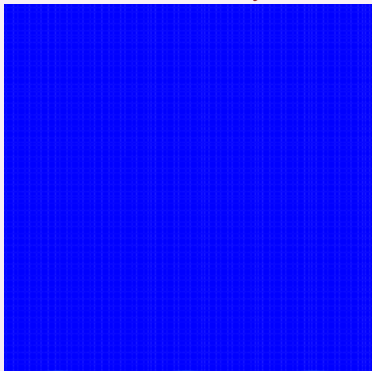
◀ Geometry

▶ Play

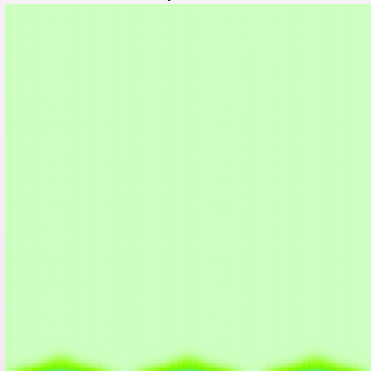
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



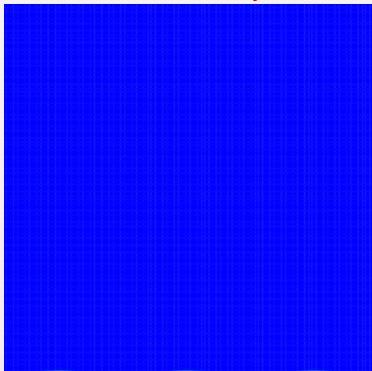
◀ Geometry

▶ Play

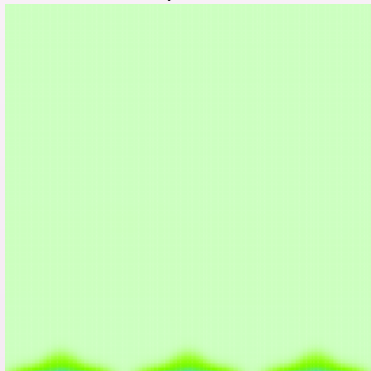
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



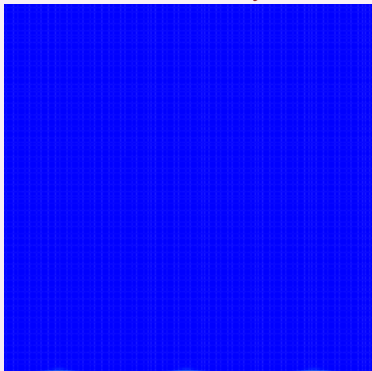
◀ Geometry

▶ Play

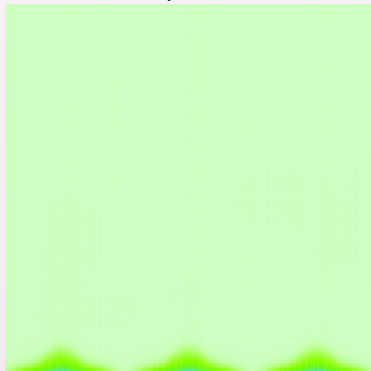
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



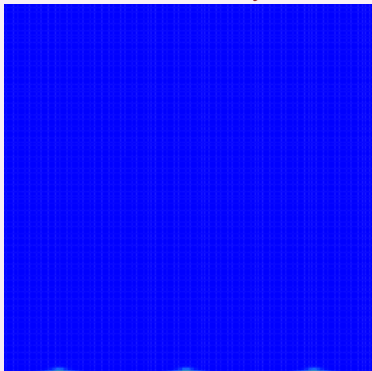
◀ Geometry

▶ Play

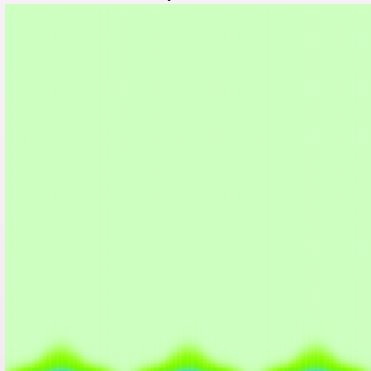
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



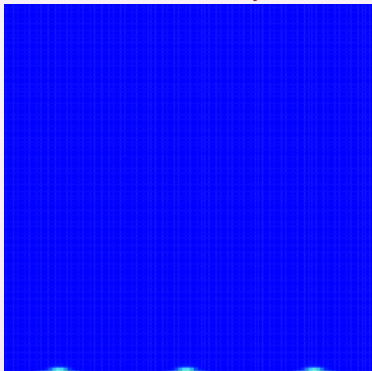
◀ Geometry

▶ Play

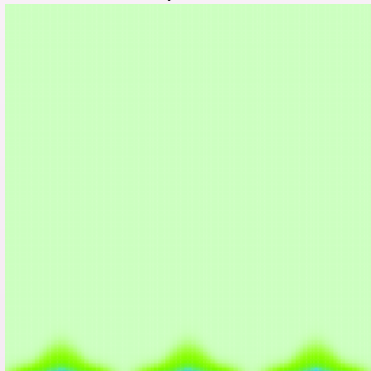
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



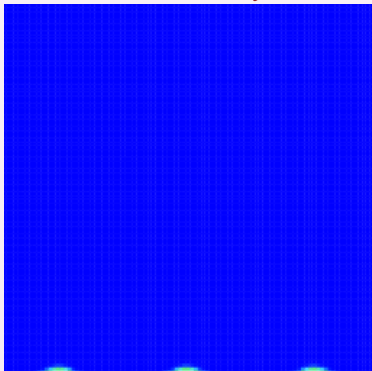
◀ Geometry

▶ Play

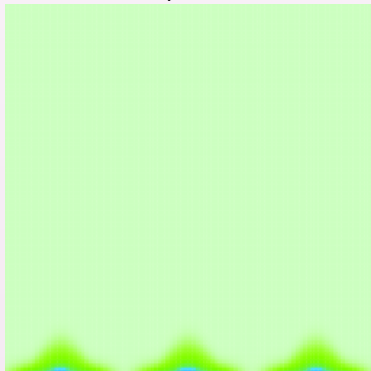
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



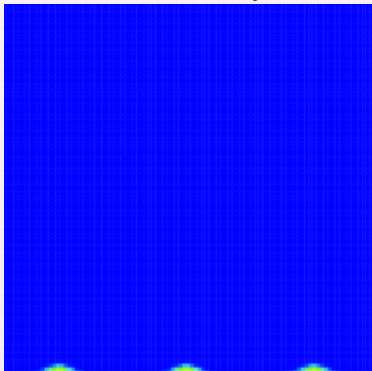
◀ Geometry

▶ Play

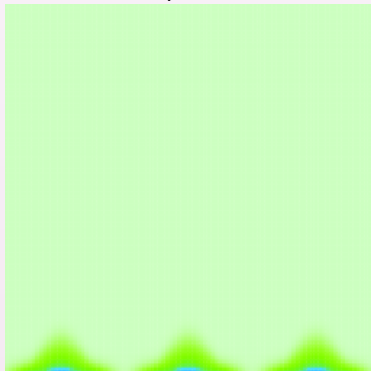
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



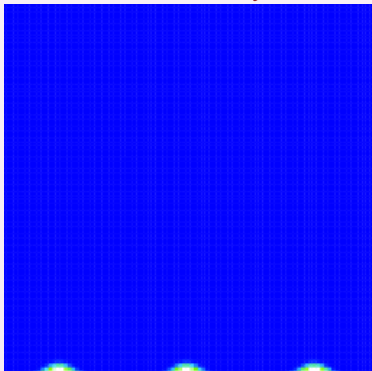
◀ Geometry

▶ Play

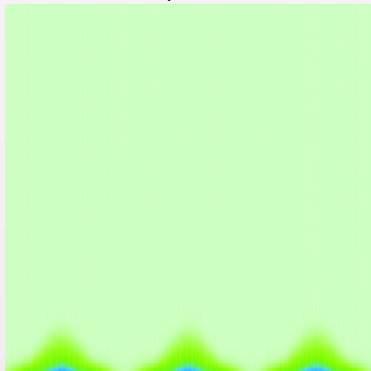
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



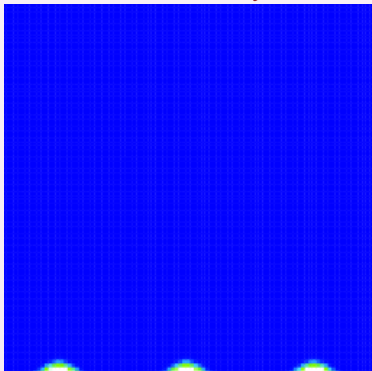
◀ Geometry

▶ Play

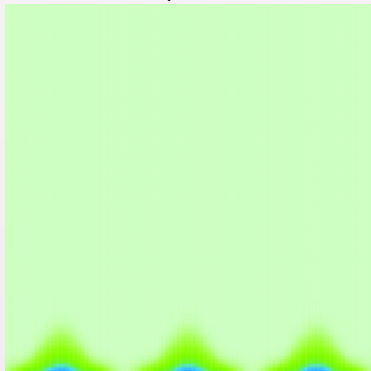
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



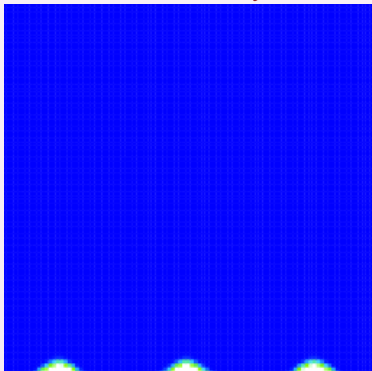
◀ Geometry

▶ Play

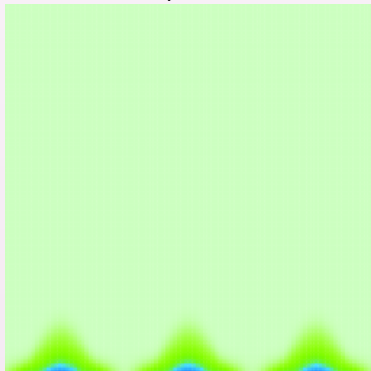
▶▶ Skip

NUCLEATING BUBBLES

Mass Fraction y



Temperature T



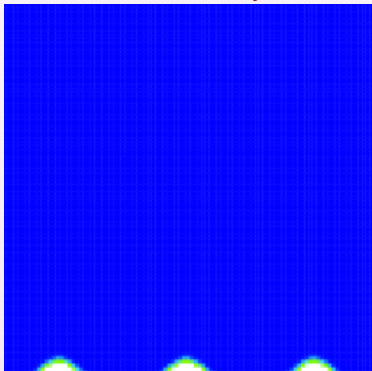
◀ Geometry

▶ Play

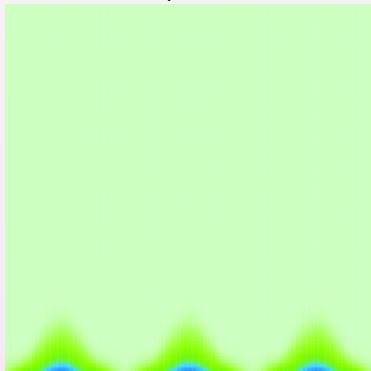
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NUCLEATING BUBBLES

Mass Fraction y



Temperature T



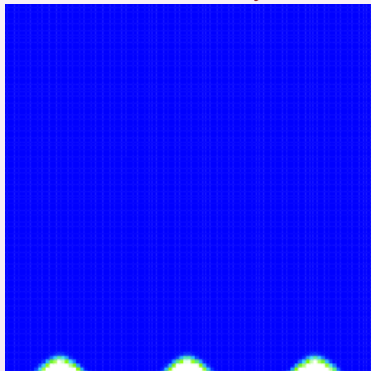
◀ Geometry

▶ Play

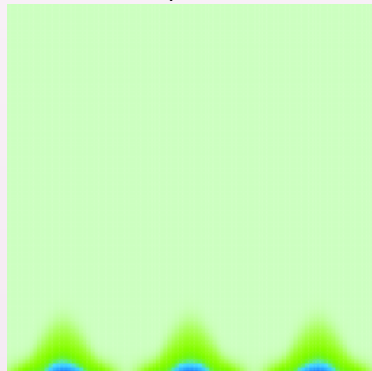
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NUCLEATING BUBBLES

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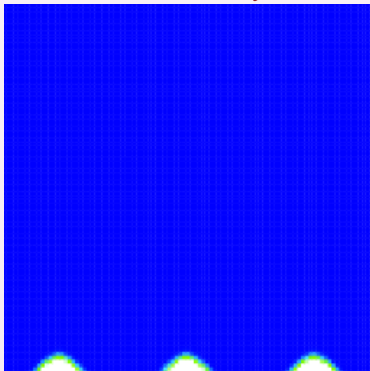
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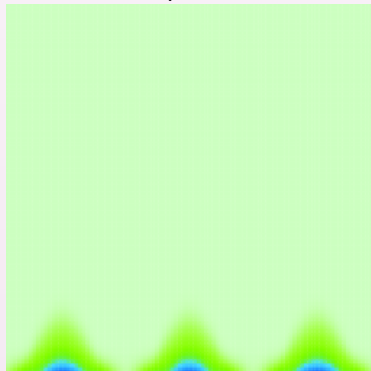
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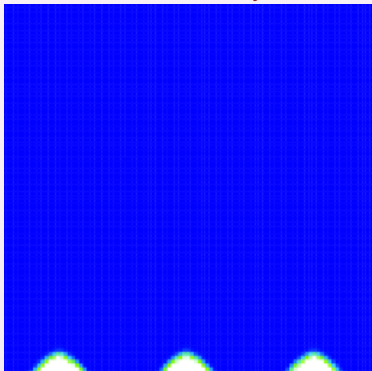
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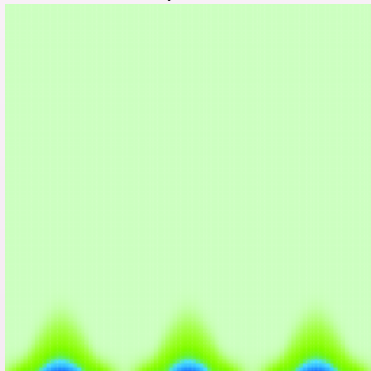
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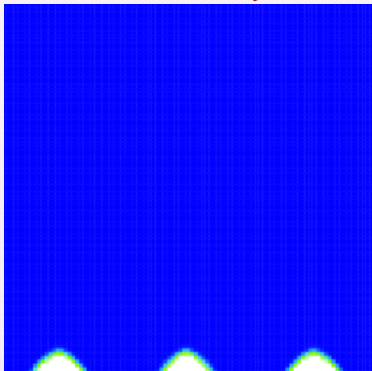
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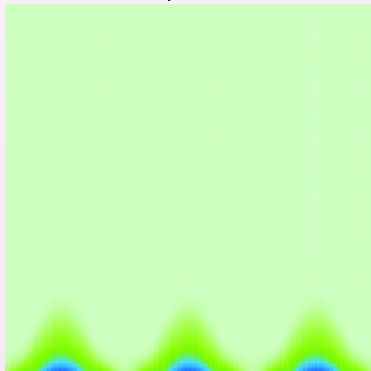
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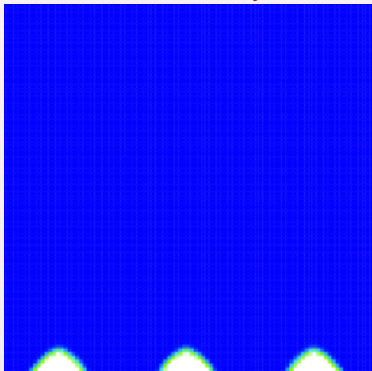
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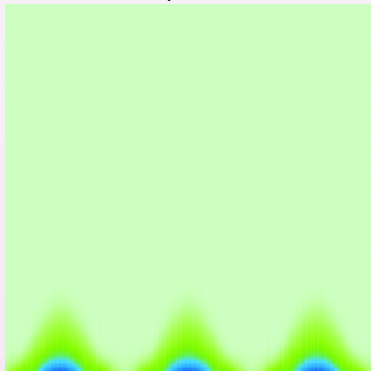
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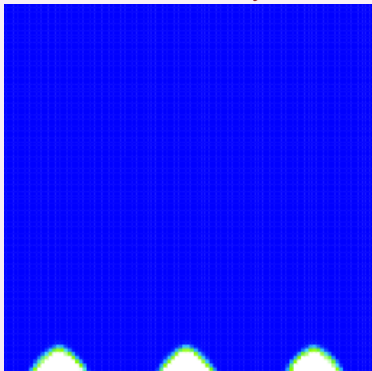
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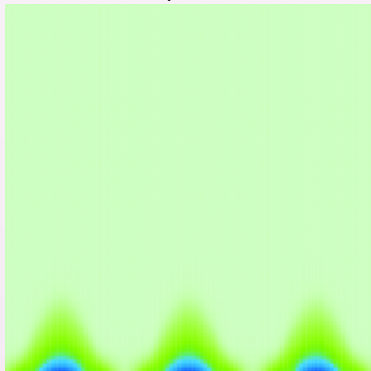
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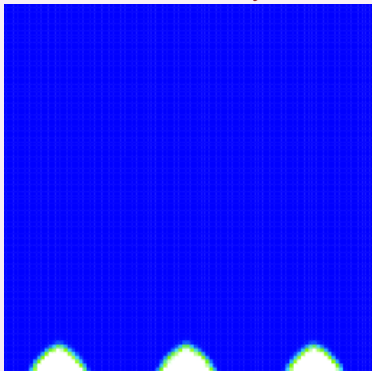
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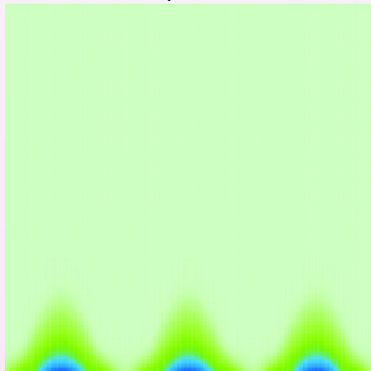
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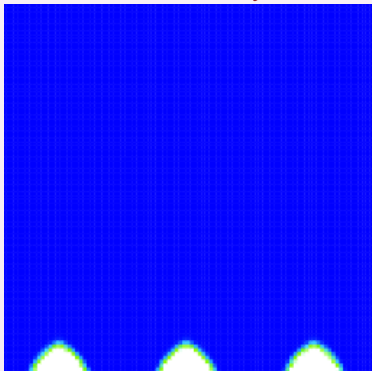
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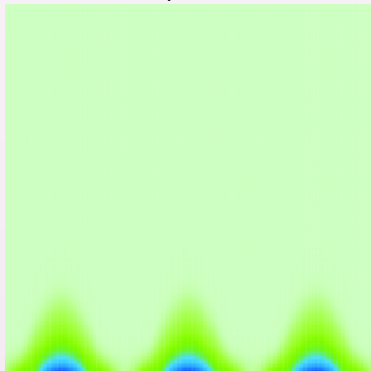
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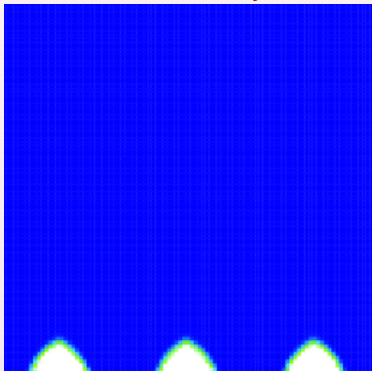
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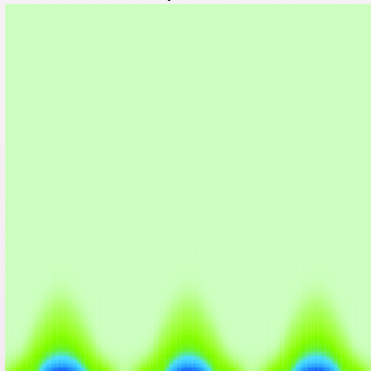
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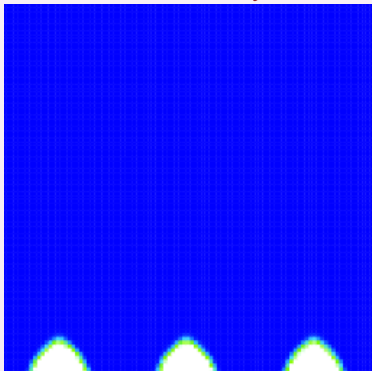
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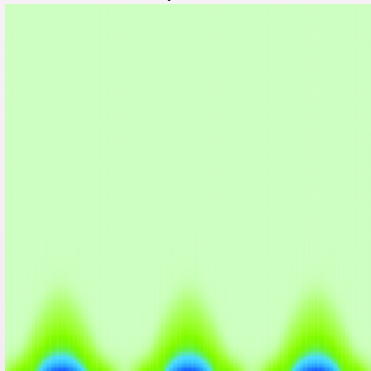
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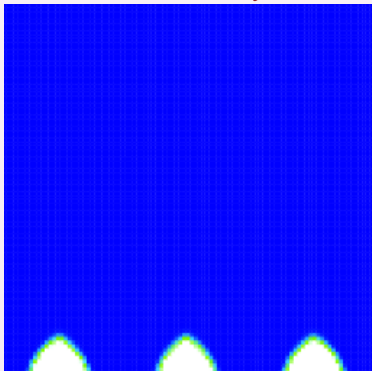
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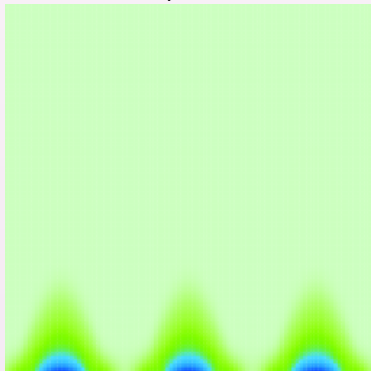
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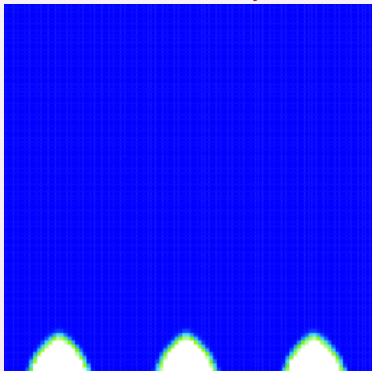
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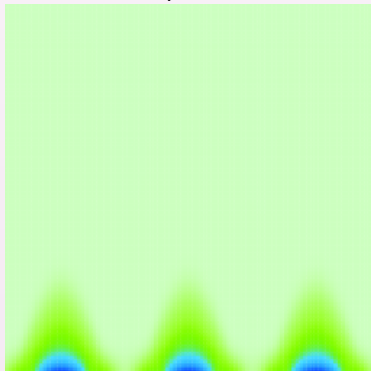
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NUCLEATING BUBBLES

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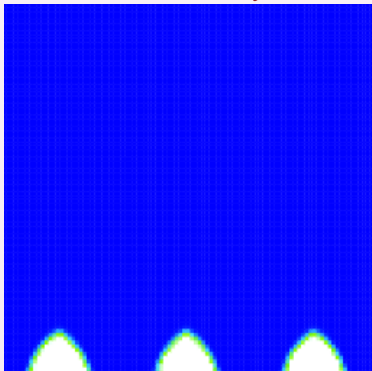
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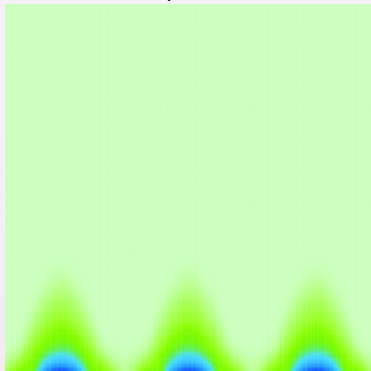
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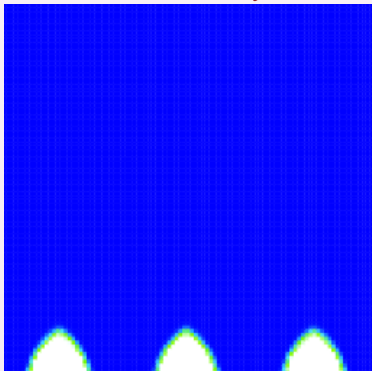
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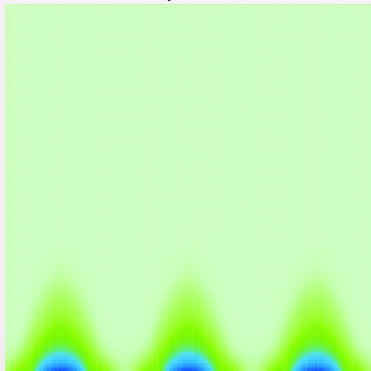
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Temperature T



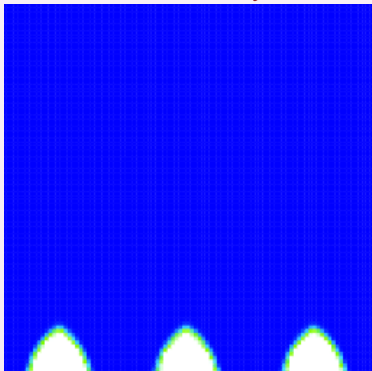
◀ Geometry

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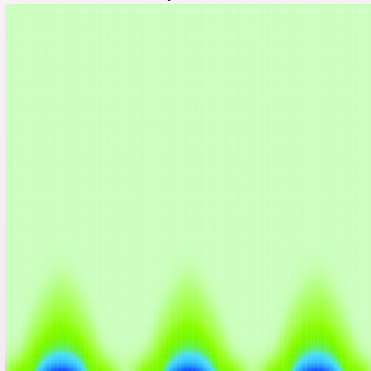
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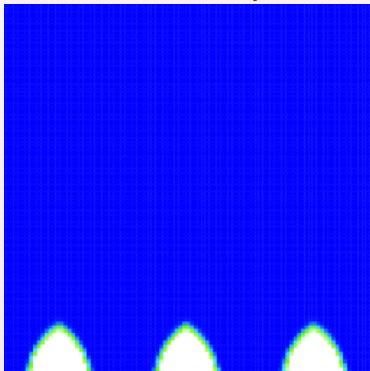
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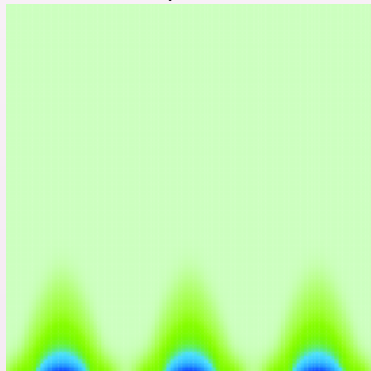
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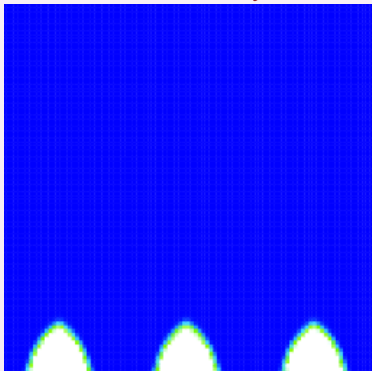
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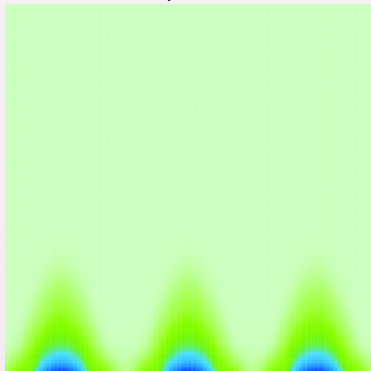
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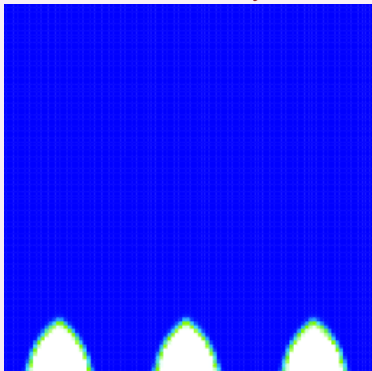
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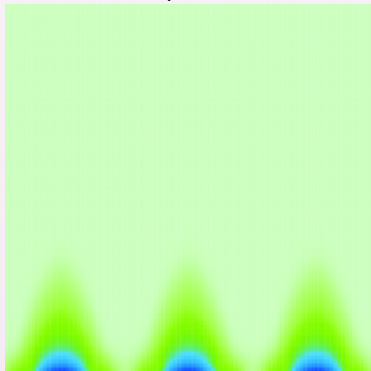
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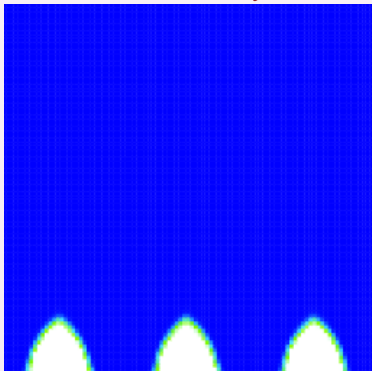
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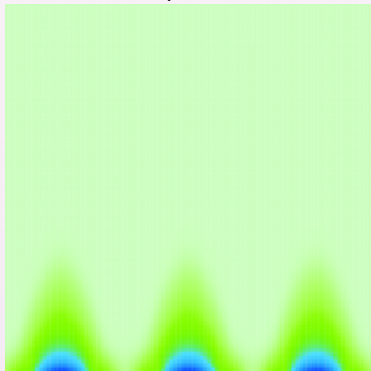
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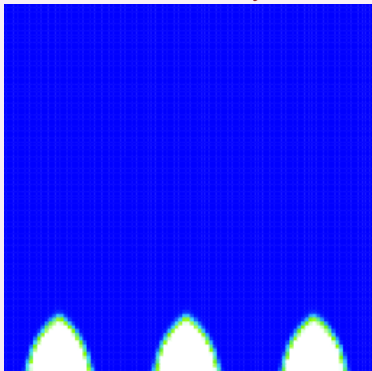
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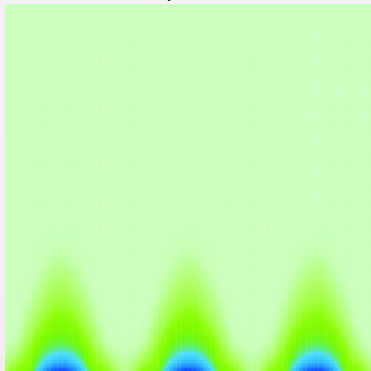
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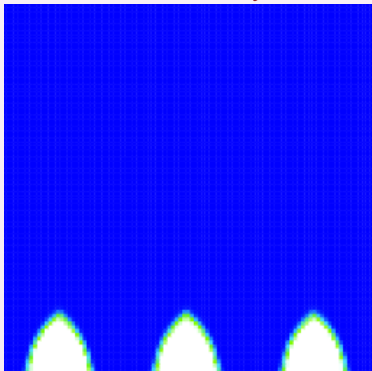
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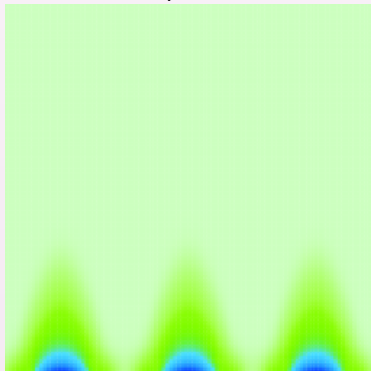
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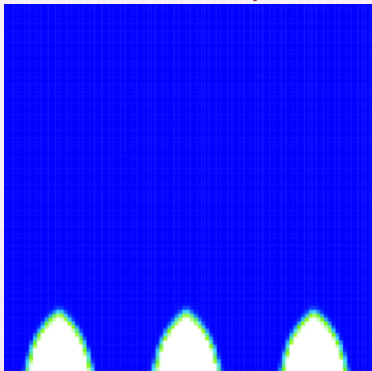
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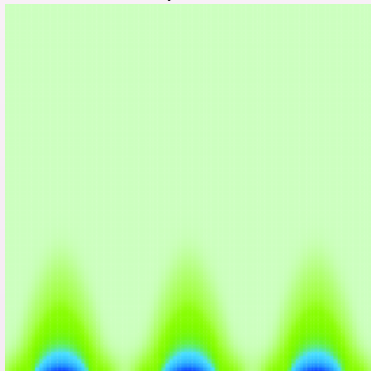
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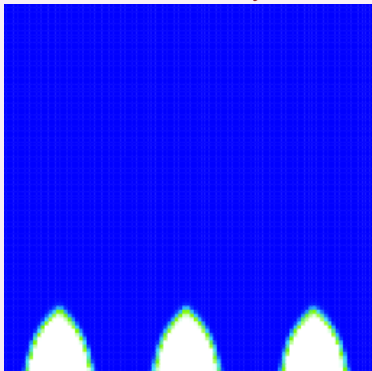
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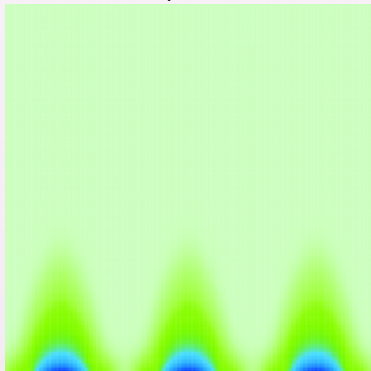
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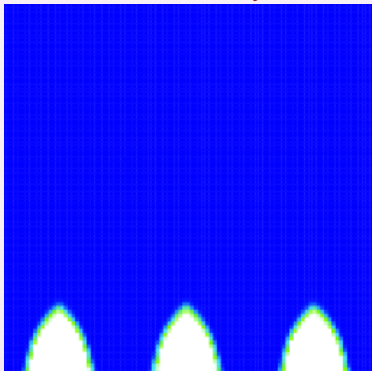
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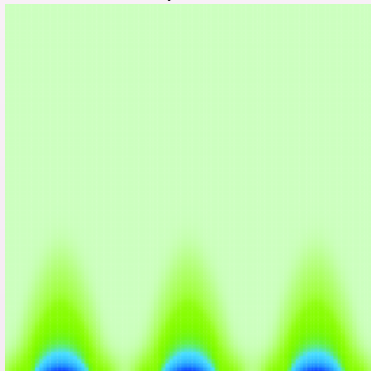
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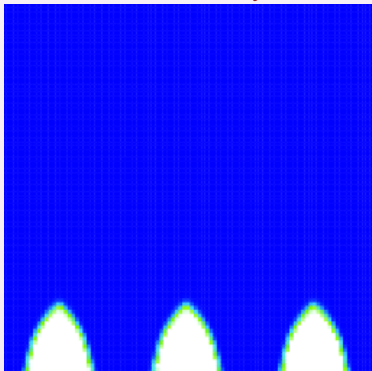
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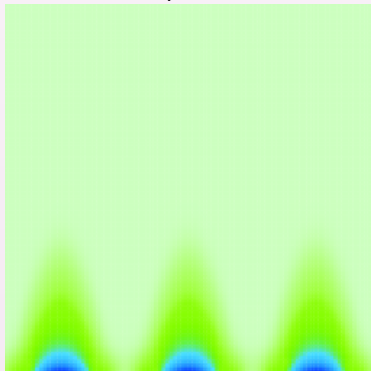
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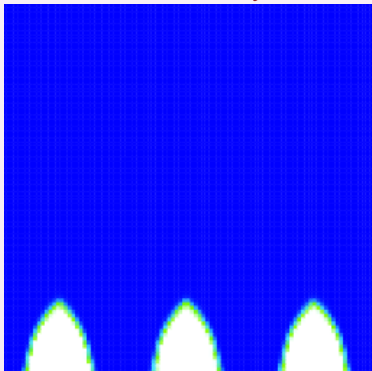
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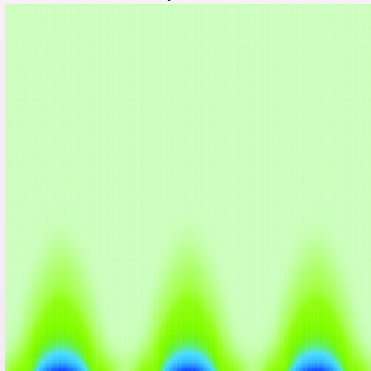
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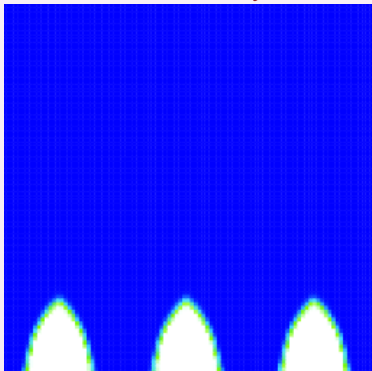
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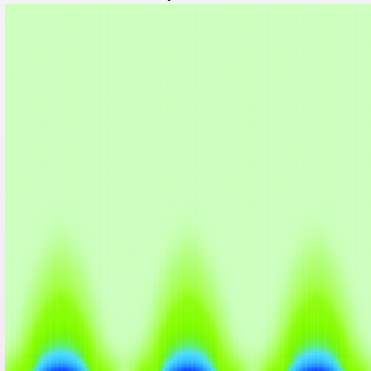
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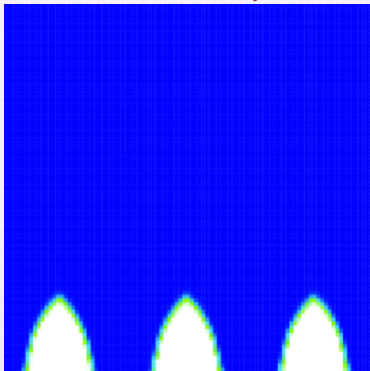
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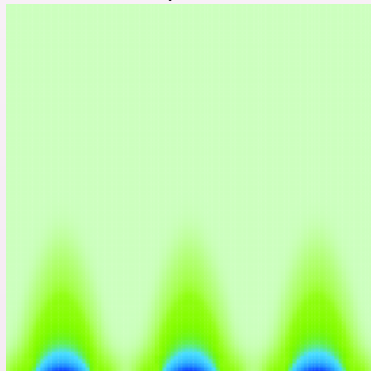
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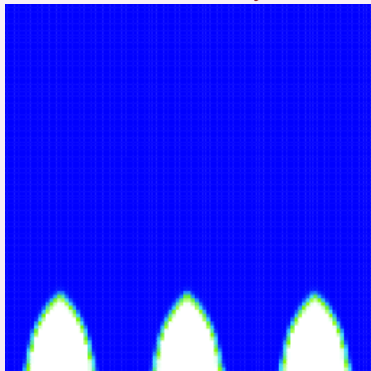
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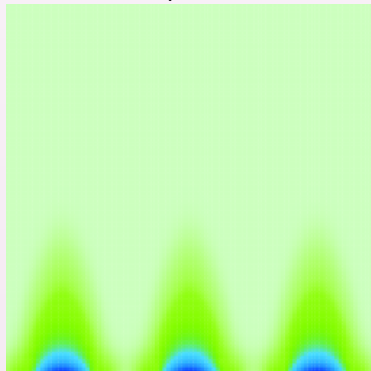
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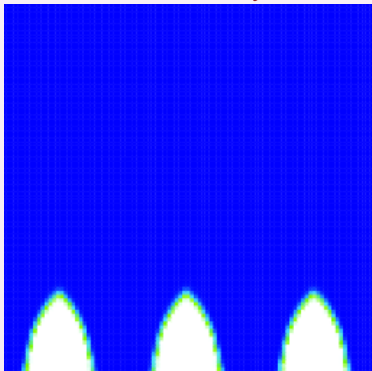
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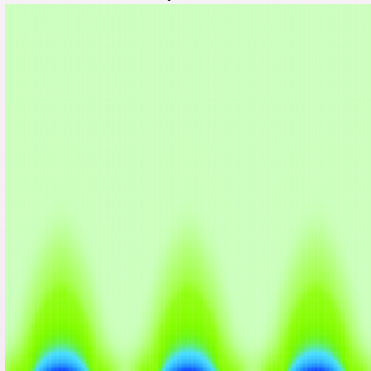
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◀ Geometry

▶ Play

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OUTLINE

- 1 Model
- 2 Numerical Method
- 3 Numerical Tests
- 4 Conclusion**

LIQUID-VAPOR PHASE TRANSITION

- Diffuse Interface Model
 - global EOS always at equilibrium (entropy maximization),
 - strict hyperbolicity of the Euler system,
 - uniqueness of Liu solution for the Riemann problem;
- Relaxation Approach
 - 6 (or 5) equation system with relaxation terms;
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 - operator splitting,
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SPEED OF SOUND

$$c^2 \stackrel{\text{def}}{=} \tau^2 \left(P^{\text{eq}} \frac{\partial P^{\text{eq}}}{\partial \varepsilon} \Big|_{\tau} - \frac{\partial P^{\text{eq}}}{\partial \tau} \Big|_{\varepsilon} \right) = \overset{0}{-\tau^2 T^{\text{eq}}} \begin{bmatrix} P^{\text{eq}}, & -1 \end{bmatrix} \begin{bmatrix} S_{\varepsilon\varepsilon}^{\text{eq}} & S_{\tau\varepsilon}^{\text{eq}} \\ S_{\tau\varepsilon}^{\text{eq}} & S_{\tau\tau}^{\text{eq}} \end{bmatrix} \begin{bmatrix} P^{\text{eq}} \\ -1 \end{bmatrix} \leq 0$$

HESSIAN MATRIX OF $w \mapsto s^{\text{eq}}$

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$$\mathbf{v}^T d^2 s^{\text{eq}}(\mathbf{w}) \mathbf{v} < 0 \quad \forall \mathbf{v} \neq 0,$$

- for all w equilibrium mixture state

$$\exists \mathbf{v}(\mathbf{w}) \neq 0 \text{ s.t. } (\mathbf{v}(\mathbf{w}))^T d^2 s^{\text{eq}}(\mathbf{w}) \mathbf{v}(\mathbf{w}) = 0.$$

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$$\forall \mathbf{w} \text{ equilibrium mixture state, } \mathbf{v}(\mathbf{w}) \stackrel{?}{=} [P^{\text{eq}}(\mathbf{w}), -1]$$

SPEED OF SOUND

$$c^2 \stackrel{\text{def}}{=} \tau^2 \left(P^{\text{eq}} \frac{\partial P^{\text{eq}}}{\partial \varepsilon} \Big|_{\tau} - \frac{\partial P^{\text{eq}}}{\partial \tau} \Big|_{\varepsilon} \right) = \overset{0}{-\tau^2 T^{\text{eq}}} \begin{bmatrix} P^{\text{eq}}, & -1 \end{bmatrix} \begin{bmatrix} S_{\varepsilon\varepsilon}^{\text{eq}} & S_{\tau\varepsilon}^{\text{eq}} \\ S_{\tau\varepsilon}^{\text{eq}} & S_{\tau\tau}^{\text{eq}} \end{bmatrix} \begin{bmatrix} P^{\text{eq}} \\ -1 \end{bmatrix} \leq 0$$

HESSIAN MATRIX OF $w \mapsto s^{\text{eq}}$

- for all w pure phase state

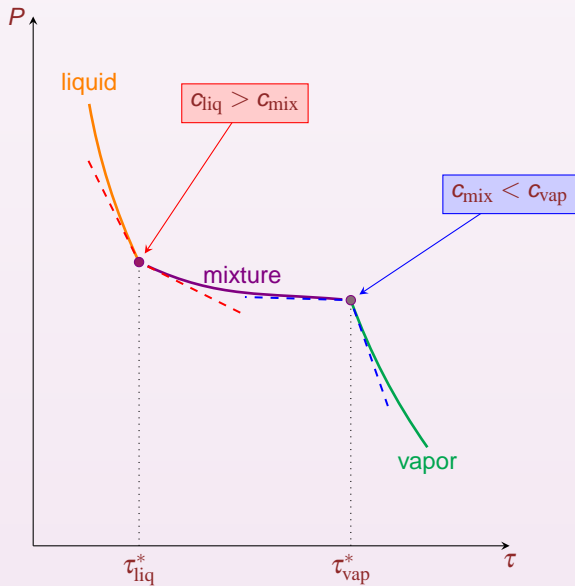
$$\mathbf{v}^T d^2 s^{\text{eq}}(\mathbf{w}) \mathbf{v} < 0 \quad \forall \mathbf{v} \neq 0,$$

- for all w equilibrium mixture state

$$\exists \mathbf{v}(\mathbf{w}) \neq 0 \text{ s.t. } (\mathbf{v}(\mathbf{w}))^T d^2 s^{\text{eq}}(\mathbf{w}) \mathbf{v}(\mathbf{w}) = 0.$$

$$\forall \mathbf{w} \text{ equilibrium mixture state, } \mathbf{v}(\mathbf{w}) \stackrel{?}{\not\propto} [P^{\text{eq}}(\mathbf{w}), -1]$$

ISENTROPIC CURVES



STIFFENED GAS FOR WATER

$$(\tau_\alpha, \varepsilon_\alpha) \mapsto s_\alpha = c_{v\alpha} \ln(\varepsilon_\alpha - q_\alpha - \pi_\alpha \tau_\alpha) + c_{v\alpha} (\gamma_\alpha - 1) \ln \tau_\alpha + m_\alpha$$

Phase	c_v [J/(kg·K)]	γ	π [Pa]	q [J/kg]	m [J/(kg·K)]
Water	1816.2	2.35	10^9	-1167.056×10^3	-32765.55596
Steam	1040.14	1.43	0	2030.255×10^3	-33265.65947

TABLE: Parameters proposed by [Le Metayer] for water.

$$(P, T) \mapsto \varepsilon_\alpha = c_{v\alpha} T \frac{P + \pi_\alpha \gamma_\alpha}{P + \pi_\alpha} + q_\alpha, \quad (P, T) \mapsto \tau_\alpha = c_{v\alpha} (\gamma_\alpha - 1) \frac{T}{P + \pi_\alpha}.$$

$$\left. \begin{array}{l} T^i = 278\text{K} \dots 610\text{K}, \\ g_1(P, T^i) = g_2(P, T^i) \Rightarrow P^{\text{sat}}(T^i) \end{array} \right\} \Rightarrow \mathfrak{A} = \left\{ (T^i, P^{\text{sat}}(T^i)) \right\}_{i=0}^{83}$$

\hat{P}^{sat} defined by using a least square approximation of \mathfrak{A} :

$$T \mapsto P^{\text{sat}}(T) \approx \hat{P}^{\text{sat}}(T) \stackrel{\text{def}}{=} \exp \left(\sum_{k=-8}^{k=8} a_k T^k \right)$$

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WATER TABULATED EOS

$$\left. \begin{array}{l} T^i = 278\text{K} \dots 610\text{K}, \\ \epsilon_{\alpha}^{\text{sat}}(T^i), \tau_{\alpha}^{\text{sat}}(T^i) \text{ found in the tables} \end{array} \right\} \Rightarrow \left\{ \begin{array}{l} \mathfrak{A} = \left\{ \left(T_i, \frac{1}{\epsilon_{\text{vap}}^{\text{sat}}(T_i)} \right) \right\}_i \\ \mathfrak{B} = \left\{ \left(T_i, \frac{\epsilon_{\text{liq}}^{\text{sat}}(T_i)}{\epsilon_{\text{vap}}^{\text{sat}}(T_i)} \right) \right\}_i \\ \mathfrak{C} = \left\{ \left(T_i, \frac{1}{\tau_{\text{vap}}^{\text{sat}}(T_i)} \right) \right\}_i \\ \mathfrak{D} = \left\{ \left(T_i, \frac{\tau_{\text{liq}}^{\text{sat}}(T_i)}{\tau_{\text{vap}}^{\text{sat}}(T_i)} \right) \right\}_i \end{array} \right.$$

$\widehat{\epsilon}_{\alpha}^{\text{sat}}$ and $\widehat{\tau}_{\alpha}^{\text{sat}}$ defined by using a least square approximation of \mathfrak{A} , \mathfrak{B} , \mathfrak{C} and \mathfrak{D} :

$$T \mapsto \epsilon_{\text{vap}}^{\text{sat}} \approx \widehat{\epsilon}_{\text{vap}}^{\text{sat}} \stackrel{\text{def}}{=} \frac{1}{\sum_{k=0}^6 a_k T^k}$$

$$T \mapsto \epsilon_{\text{liq}}^{\text{sat}} \approx \widehat{\epsilon}_{\text{liq}}^{\text{sat}} \stackrel{\text{def}}{=} \widehat{\epsilon}_{\text{vap}}^{\text{sat}}(T) \sum_{k=0}^6 b_k T^k$$

$$T \mapsto \tau_{\text{vap}}^{\text{sat}} \approx \widehat{\tau}_{\text{vap}}^{\text{sat}} \stackrel{\text{def}}{=} \frac{1}{\sum_{k=0}^8 c_k T^k}$$

$$T \mapsto \tau_{\text{liq}}^{\text{sat}} \approx \widehat{\tau}_{\text{liq}}^{\text{sat}} \stackrel{\text{def}}{=} \widehat{\tau}_{\text{vap}}^{\text{sat}}(T) \sum_{k=0}^9 d_k T^k$$