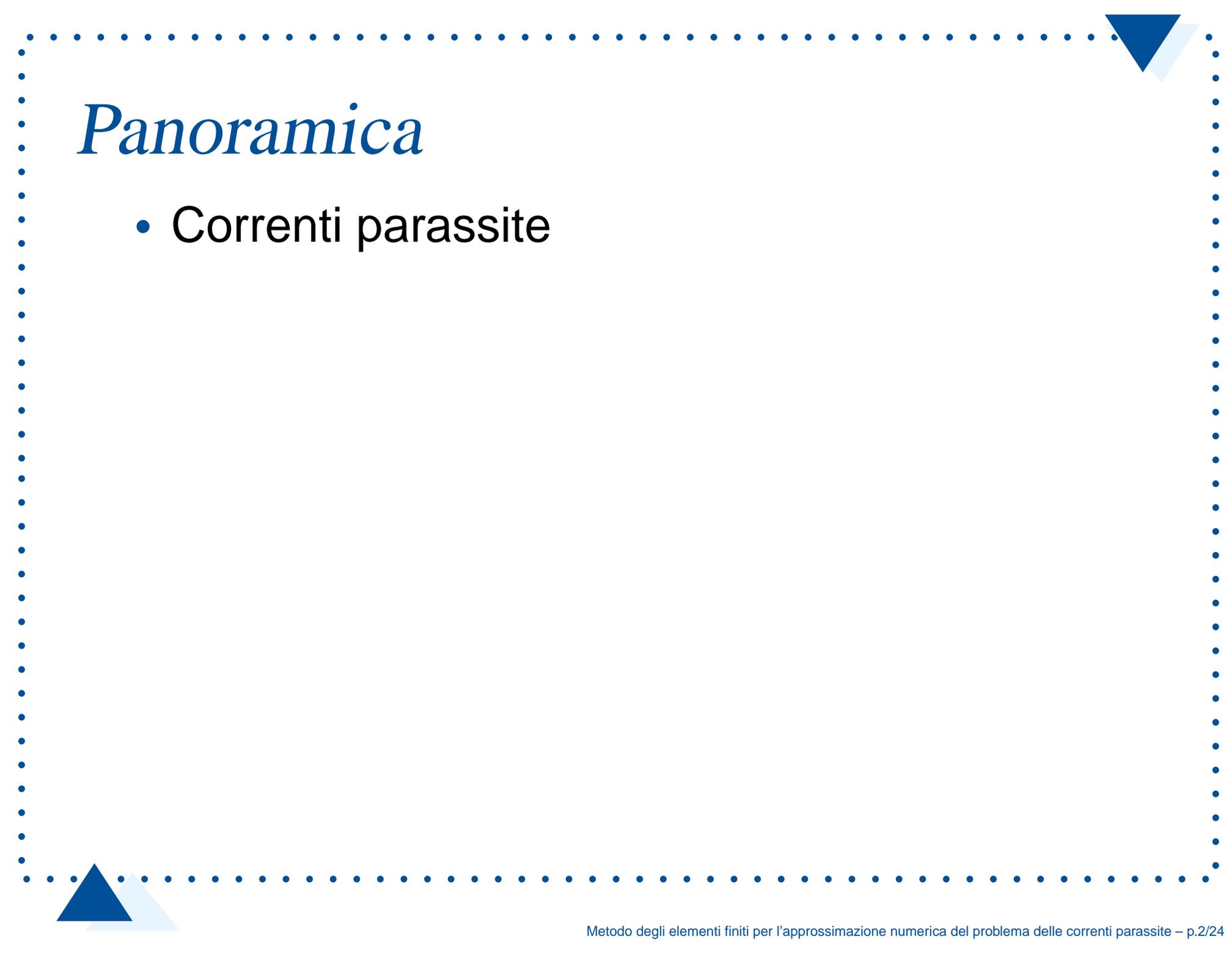
The slide features a decorative border of small blue dots. In the top-right and bottom-left corners, there are blue triangles pointing towards the center, with a lighter blue shadow effect behind them.

Metodo degli elementi finiti per l'approssimazione numerica del problema delle correnti parassite

Gloria Faccanoni

matr. 561907

The slide features a decorative border of small blue dots. In the top-right and bottom-left corners, there are blue triangles pointing towards the center, with a lighter blue shadow effect behind them.

Panoramica

- Correnti parassite



Panoramica

- Correnti parassite
- Formulazione variazionale in \mathbf{H}



Panoramica

- Correnti parassite
- Formulazione variazionale in \mathbf{H}
- Potenziale magnetico scalare



Panoramica

- Correnti parassite
- Formulazione variazionale in \mathbf{H}
- Potenziale magnetico scalare
- Elementi finiti



Panoramica

- Correnti parassite
- Formulazione variazionale in \mathbf{H}
- Potenziale magnetico scalare
- Elementi finiti
- Iterazione per sottodomini



Panoramica

- Correnti parassite
- Formulazione variazionale in \mathbf{H}
- Potenziale magnetico scalare
- Elementi finiti
- Iterazione per sottodomini
- Implementazione e prove numeriche

Correnti parassite

Equazioni di Maxwell in regime armonico

$$\begin{cases} \mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H} \\ \mathbf{rot} \mathbf{H} = i\omega\varepsilon\mathbf{E} + \sigma\mathbf{E} + \mathbf{J}_e \end{cases}$$

Trascurando le correnti di spostamento si ottiene il modello per le correnti parassite:

Correnti parassite

Equazioni di Maxwell in regime armonico

$$\begin{cases} \text{rot } \mathbf{E} = -i\omega\mu\mathbf{H} \\ \text{rot } \mathbf{H} = i\omega\varepsilon\mathbf{E} + \sigma\mathbf{E} + \mathbf{J}_e \end{cases}$$

Trascurando le correnti di spostamento si ottiene il modello per le correnti parassite:

$$\begin{cases} \text{rot } \mathbf{E} = -i\omega\mu\mathbf{H} \\ \text{rot } \mathbf{H} = \sigma\mathbf{E} + \mathbf{J}_e \end{cases}$$

Dominio

- $\Omega \subset \mathbb{R}^3$ dominio computazionale

Dominio

- $\Omega \subset \mathbb{R}^3$ dominio computazionale
- $\bar{\Omega}_C \subset \Omega$ conduttore

Dominio

- $\Omega \subset \mathbb{R}^3$ dominio computazionale
- $\bar{\Omega}_C \subset \Omega$ conduttore
- $\Omega_I := \Omega \setminus \bar{\Omega}_C$ isolante perfetto

Dominio

- $\Omega \subset \mathbb{R}^3$ dominio computazionale
- $\bar{\Omega}_C \subset \Omega$ conduttore
- $\Omega_I := \Omega \setminus \bar{\Omega}_C$ isolante perfetto
- $\Gamma := \partial\Omega_I \cap \partial\Omega_C$ interfaccia \Rightarrow

$$\begin{cases} \partial\Omega_C = \Gamma \\ \partial\Omega_I = \partial\Omega \cup \Gamma \end{cases}$$

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$
- $\mu(\mathbf{x})$ uniformemente definita positiva in Ω

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$
- $\mu(\mathbf{x})$ uniformemente definita positiva in Ω
- $\sigma(\mathbf{x})$

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$
- $\mu(\mathbf{x})$ uniformemente definita positiva in Ω
- $\sigma(\mathbf{x})$
 - uniformemente definita positiva in Ω_C

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$
- $\mu(\mathbf{x})$ uniformemente definita positiva in Ω
- $\sigma(\mathbf{x})$
 - uniformemente definita positiva in Ω_C
 - 0 in Ω_I

Ipotesi

- $\mu(\mathbf{x})$ e $\sigma(\mathbf{x})$ sono matrici reali 3×3 simmetriche con coefficienti in $L^\infty(\Omega)$
- $\mu(\mathbf{x})$ uniformemente definita positiva in Ω
- $\sigma(\mathbf{x})$
 - uniformemente definita positiva in Ω_C
 - 0 in Ω_I
- $\mathbf{H} \times \mathbf{n} = \mathbf{0}$ su $\partial\Omega$

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e \text{ in } \Omega$$

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e \text{ in } \Omega$$

[Poiché $\sigma|_{\Omega_I} = 0$]

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e \text{ in } \Omega$$

$$\mathbf{rot} \mathbf{H}_I = \mathbf{J}_{e,I} \text{ in } \Omega_I$$

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e \text{ in } \Omega$$

$$\mathbf{rot} \mathbf{H}_I = \mathbf{J}_{e,I} \text{ in } \Omega_I$$

[Pertanto il dato $\mathbf{J}_{e,I}$ deve soddisfare]

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e \quad \text{in } \Omega$$

$$\mathbf{rot} \mathbf{H}_I = \mathbf{J}_{e,I} \quad \text{in } \Omega_I$$

$$\operatorname{div} \mathbf{J}_{e,I} = 0 \quad \text{in } \Omega_I$$

$$\langle \mathbf{J}_{e,I} \cdot \mathbf{n}_I, 1 \rangle_{\Gamma_j} = 0 \quad \forall j = 1, \dots, p_\Gamma - 1$$

Vincoli per l'esistenza

$$\text{rot } \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e$$

$$\text{rot } \mathbf{H}_I = \mathbf{J}_{e,I} \quad \text{in } \Omega_I$$

$$\text{div } \mathbf{J}_{e,I} = 0 \quad \text{in } \Omega_I$$

$$\langle \mathbf{J}_{e,I} \cdot \mathbf{n}_I, 1 \rangle_{\Gamma_j} = 0 \quad \forall j = 1, \dots, p_\Gamma - 1$$

[Poiché $\mathbf{H} \times \mathbf{n} = \mathbf{0}$ su $\partial\Omega$ il dato \mathbf{J}_e deve soddisfare inoltre]

Vincoli per l'esistenza

$$\mathbf{rot} \mathbf{H} = \sigma \mathbf{E} + \mathbf{J}_e$$

$$\mathbf{rot} \mathbf{H}_I = \mathbf{J}_{e,I} \quad \text{in } \Omega_I$$

$$\mathbf{div} \mathbf{J}_{e,I} = 0 \quad \text{in } \Omega_I$$

$$\langle \mathbf{J}_{e,I} \cdot \mathbf{n}_I, 1 \rangle_{\Gamma_j} = 0 \quad \forall j = 1, \dots, p_\Gamma - 1$$

$$\mathbf{J}_{e,I} \cdot \mathbf{n} = 0 \quad \text{su } \partial\Omega$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = - i\omega\mu\mathbf{H}$$

[Moltiplicando per una funzione test $\mathbf{v} \in V \subset H_0(\mathbf{rot}; \Omega)$ ed integrando su tutto il dominio Ω ...]

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

[Utilizzando la formula di Green...]

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{E} \cdot \mathbf{rot} \bar{\mathbf{v}} = 0$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{E} \cdot \mathbf{rot} \bar{\mathbf{v}} = 0$$

$$[Se \quad V := \{\mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{0} \text{ in } \Omega_I\}]$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{E} \cdot \mathbf{rot} \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega_C} \mathbf{E}_C \cdot \mathbf{rot} \bar{\mathbf{v}}_C = 0$$

Formulazione variazionale in \mathbf{H}

$$\mathbf{rot} \mathbf{E} = -i\omega\mu\mathbf{H}$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{rot} \mathbf{E} \cdot \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega} \mathbf{E} \cdot \mathbf{rot} \bar{\mathbf{v}} = 0$$

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega_C} \mathbf{E}_C \cdot \mathbf{rot} \bar{\mathbf{v}}_C = 0$$

$$[\mathbf{rot} \mathbf{H} = \sigma\mathbf{E} + \mathbf{J}_e \Rightarrow \mathbf{E}_C = \sigma^{-1}(\mathbf{rot} \mathbf{H}_C - \mathbf{J}_{e,C})]$$

Formulazione variazionale in \mathbf{H}

$$\int_{\Omega} i\omega\mu\mathbf{H} \cdot \bar{\mathbf{v}} + \int_{\Omega_C} \sigma^{-1} \mathbf{rot} \mathbf{H}_C \cdot \mathbf{rot} \bar{\mathbf{v}}_C =$$
$$= \int_{\Omega_C} \sigma^{-1} \mathbf{J}_{e,C} \cdot \mathbf{rot} \bar{\mathbf{v}}_C$$

dove

$$\mathbf{H} \in V^{\mathbf{J}_{e,I}} := \{ \mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{J}_{e,I} \text{ in } \Omega_I \}$$

$$\mathbf{v} \in V = \{ \mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{0} \text{ in } \Omega_I \}$$

Esistenza ed unicità

$\mathbf{H}_e \in H_0(\mathbf{rot}; \Omega)$ tale che

$$\begin{cases} \mathbf{rot} \mathbf{H}_{e,I} = \mathbf{J}_{e,I} & \text{in } \Omega_I \\ \mathbf{H}_{e,I} \times \mathbf{n} = \mathbf{0} & \text{su } \partial\Omega_I \setminus \Gamma \end{cases}$$

Indichiamo con $\mathbf{Z} := \mathbf{H} - \mathbf{H}_e$, allora $\mathbf{Z} \in V$ ed il problema diviene...

Esistenza ed unicità

Cercare $\mathbf{Z} \in V$ tale che $\forall \mathbf{v} \in V$

$$\mathcal{A}(\mathbf{Z}, \mathbf{v}) = L(\mathbf{v})$$

dove

$$\mathcal{A}(\mathbf{w}, \mathbf{v}) := \int_{\Omega_C} \sigma^{-1} \mathbf{rot} \mathbf{w}_C \cdot \mathbf{rot} \bar{\mathbf{v}}_C + i\omega \int_{\Omega} \mu \mathbf{w} \cdot \bar{\mathbf{v}}$$

$$L(\mathbf{v}) := -\mathcal{A}(\mathbf{H}_e, \mathbf{v}) + \int_{\Omega_C} \sigma^{-1} \mathbf{J}_{e,C} \cdot \mathbf{rot} \bar{\mathbf{v}}_C$$



Potenziale magnetico scalare

Ω_I è semplicemente connesso

Potenziale magnetico scalare

Ω_I è semplicemente connesso

$$\mathbf{v} \in V = \{ \mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{0} \text{ in } \Omega_I \}$$

Potenziale magnetico scalare

Ω_I è semplicemente connesso

$$\mathbf{v} \in V = \{ \mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{0} \text{ in } \Omega_I \}$$

$$\mathbf{v}|_{\Omega_I} = \nabla \psi_I \in H(\mathbf{rot}; \Omega_I)$$

dove $\psi_I \in H_{0,\partial\Omega}^1(\Omega_I)$ (infatti $\mathbf{v}_I \times \mathbf{n} = \mathbf{0}$ su $\partial\Omega$
permette di scegliere $\psi_I = 0$ su $\partial\Omega$)

Potenziale magnetico scalare

Ω_I è semplicemente connesso

$$\mathbf{v} \in V = \{ \mathbf{v} \in H_0(\mathbf{rot}; \Omega) \mid \mathbf{rot} \mathbf{v}_I = \mathbf{0} \text{ in } \Omega_I \}$$

$$\mathbf{v}|_{\Omega_I} = \nabla \psi_I \in H(\mathbf{rot}; \Omega_I)$$

dove $\psi_I \in H_{0,\partial\Omega}^1(\Omega_I)$ (infatti $\mathbf{v}_I \times \mathbf{n} = \mathbf{0}$ su $\partial\Omega$ permette di scegliere $\psi_I = 0$ su $\partial\Omega$)

Introduciamo allora lo spazio

$$W := \{ (\mathbf{v}_C, \varphi_I) \in H(\mathbf{rot}; \Omega_C) \times H_{0,\partial\Omega}^1(\Omega_I) \mid \mathbf{v}_C \times \mathbf{n}_C + \nabla \varphi_I \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma \}$$

Formulazione bidominio

Cercare $(\mathbf{Z}_C, \psi_I) \in W$ tale che $\forall (\mathbf{v}_C, \varphi_I) \in W$

$$\int_{\Omega_C} [i\omega\mu_C \mathbf{Z}_C \cdot \bar{\mathbf{v}}_C + \sigma^{-1} \mathbf{rot} \mathbf{Z}_C \cdot \mathbf{rot} \bar{\mathbf{v}}_C] + \\ + \int_{\Omega_I} [i\omega\mu_I \nabla \psi_I \cdot \nabla \bar{\varphi}_I] = F(\mathbf{v}_C, \varphi_I)$$

dove

$$F(\mathbf{v}_C, \varphi_I) := - \int_{\Omega_I} [i\omega\mu_I \mathbf{H}_{e,I} \cdot \nabla \bar{\varphi}_I] + \\ + \int_{\Omega_C} [\sigma^{-1} (\mathbf{J}_{e,C} - \mathbf{rot} \mathbf{H}_{e,C}) \cdot \mathbf{rot} \bar{\mathbf{v}}_C - i\omega\mu_C \mathbf{H}_{e,C} \cdot \bar{\mathbf{v}}_C]$$

Approssimazione di Galerkin

$$W := \{(\mathbf{v}_C, \varphi_I) \in H(\mathbf{rot}; \Omega_C) \times H_{0, \partial\Omega}^1(\Omega_I) \mid \mathbf{v}_C \times \mathbf{n}_C + \nabla \varphi_I \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

Approssimazione di Galerkin

$$W := \{(\mathbf{v}_C, \varphi_I) \in H(\mathbf{rot}; \Omega_C) \times H_{0, \partial\Omega}^1(\Omega_I) \mid \mathbf{v}_C \times \mathbf{n}_C + \nabla \varphi_I \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

EF lineari Nédélec

EF lineari Lagrange



EF di Lagrange $\rightsquigarrow H_{0,\partial\Omega}^1(\Omega_I)$

- $V_{I,h} := \{ \psi_h \in C^0(\bar{\Omega}_I) \mid \psi_h|_K \in \mathbb{Q}_1 \ \forall K \in T_h \}$

EF di Lagrange $\rightsquigarrow H_{0,\partial\Omega}^1(\Omega_I)$

- $V_{I,h} := \{ \psi_h \in C^0(\bar{\Omega}_I) \mid \psi_h|_K \in \mathbb{Q}_1 \ \forall K \in T_h \}$
- **DOF** $\rightsquigarrow \psi_h(\mathbf{a}_j)$ (\mathbf{a}_j vertici di T_h)

EF di Lagrange $\rightsquigarrow H_{0,\partial\Omega}^1(\Omega_I)$

- $V_{I,h} := \{ \psi_h \in C^0(\bar{\Omega}_I) \mid \psi_h|_K \in \mathbb{Q}_1 \ \forall K \in T_h \}$
- **DOF** $\rightsquigarrow \psi_h(\mathbf{a}_j)$ (\mathbf{a}_j vertici di T_h)
- **base** $\rightsquigarrow \varphi_{i,h}(\mathbf{a}_j) = \delta_{ij} \quad \forall i, j = 0 \dots n_{h,L}$

EF di Nédélec $\rightsquigarrow H(\mathbf{rot}, \Omega_C)$

- $N_{C,h} := \{ \mathbf{v}_h \in H(\mathbf{rot}; \Omega_C) \mid \mathbf{v}_h|_K \in \mathbb{Q}_{0,1,1} \times \mathbb{Q}_{1,0,1} \times \mathbb{Q}_{1,1,0} \forall K \in T_h \}$

EF di Nédélec $\rightsquigarrow H(\mathbf{rot}, \Omega_C)$

- $N_{C,h} := \{ \mathbf{v}_h \in H(\mathbf{rot}; \Omega_C) \mid \mathbf{v}_h|_K \in \mathbb{Q}_{0,1,1} \times \mathbb{Q}_{1,0,1} \times \mathbb{Q}_{1,1,0} \ \forall K \in T_h \}$
- DOF $\rightsquigarrow m_i(\mathbf{v}_h) := \int_{e_i} \mathbf{v}_h \cdot \mathbf{t} ds$
(e_i spigoli di T_h)

EF di Nédélec $\rightsquigarrow H(\mathbf{rot}, \Omega_C)$

- $N_{C,h} := \{ \mathbf{v}_h \in H(\mathbf{rot}; \Omega_C) \mid \mathbf{v}_h|_K \in \mathbb{Q}_{0,1,1} \times \mathbb{Q}_{1,0,1} \times \mathbb{Q}_{1,1,0} \forall K \in T_h \}$
- DOF $\rightsquigarrow m_i(\mathbf{v}_h) := \int_{e_i} \mathbf{v}_h \cdot \mathbf{t} ds$
(e_i spigoli di T_h)
- base $\rightsquigarrow m_j(\mathbf{w}_{i,h}) = \int_{e_j} \mathbf{w}_{i,h} \cdot \mathbf{t} ds = \delta_{ij}$

Approssimazione di Galerkin

$$W := \{(\mathbf{v}_C, \varphi_I) \in H(\mathbf{rot}; \Omega_C) \times H_{0, \partial\Omega}^1(\Omega_I) \mid \\ \mathbf{v}_C \times \mathbf{n}_C + \nabla \varphi_I \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

$$W_h := \{(\mathbf{v}_{C,h}, \varphi_{I,h}) \in N_{C,h} \times V_{I,h} \mid \\ \mathbf{v}_{C,h} \times \mathbf{n}_C + \nabla \varphi_{I,h} \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

Approssimazione di Galerkin

$$W := \{(\mathbf{v}_C, \varphi_I) \in H(\mathbf{rot}; \Omega_C) \times H_{0, \partial\Omega}^1(\Omega_I) \mid \mathbf{v}_C \times \mathbf{n}_C + \nabla \varphi_I \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

$$W_h := \{(\mathbf{v}_{C,h}, \varphi_{I,h}) \in N_{C,h} \times V_{I,h} \mid \mathbf{v}_{C,h} \times \mathbf{n}_C + \nabla \varphi_{I,h} \times \mathbf{n}_I = \mathbf{0} \text{ su } \Gamma\}$$

Formulazione forte

1. $\mathbf{rot}(\sigma^{-1} \mathbf{rot} \mathbf{H}_C) + i\omega\mu_C \mathbf{H}_C = \mathbf{rot}(\sigma^{-1} \mathbf{J}_{e,C}) \quad \text{in } \Omega_C$

2. $\mathbf{div}(\mu_I \nabla \psi_I) = -\mathbf{div}(\mu_I \mathbf{H}_{e,I}) \quad \text{in } \Omega_I$

3. $\psi_I = 0 \quad \text{su } \partial\Omega_I \setminus \Gamma$

4. $\mathbf{H}_C \times \mathbf{n}_C = -\nabla \psi_I \times \mathbf{n}_I - \mathbf{H}_{e,I} \times \mathbf{n}_I \quad \text{su } \Gamma$

5. $\mu_I \nabla \psi_I \cdot \mathbf{n}_I = -\mu_C \mathbf{H}_C \cdot \mathbf{n}_C - \mu_I \mathbf{H}_{e,I} \cdot \mathbf{n}_I \quad \text{su } \Gamma$

Formulazione forte

1. $\text{rot}(\sigma^{-1} \text{rot } \mathbf{H}_C) + i\omega\mu_C \mathbf{H}_C = \text{rot}(\sigma^{-1} \mathbf{J}_{e,C}) \quad \text{in } \Omega_C$

2. $\text{div}(\mu_I \nabla \psi_I) = -\text{div}(\mu_I \mathbf{H}_{e,I}) \quad \text{in } \Omega_I$

3. $\psi_I = 0 \quad \text{su } \partial\Omega_I \setminus \Gamma$

4. $\mathbf{H}_C \times \mathbf{n}_C = -\nabla \psi_I \times \mathbf{n}_I - \mathbf{H}_{e,I} \times \mathbf{n}_I \quad \text{su } \Gamma$

5. $\mu_I \nabla \psi_I \cdot \mathbf{n}_I = -\mu_C \mathbf{H}_C \cdot \mathbf{n}_C - \mu_I \mathbf{H}_{e,I} \cdot \mathbf{n}_I \quad \text{su } \Gamma$

Formulazione forte

1. $\text{rot}(\sigma^{-1} \text{rot } \mathbf{H}_C) + i\omega\mu_C \mathbf{H}_C = \text{rot}(\sigma^{-1} \mathbf{J}_{e,C}) \quad \text{in } \Omega_C$

2. $\text{div}(\mu_I \nabla \psi_I) = -\text{div}(\mu_I \mathbf{H}_{e,I}) \quad \text{in } \Omega_I$

3. $\psi_I = 0 \quad \text{su } \partial\Omega_I \setminus \Gamma$

4. $\mathbf{H}_C \times \mathbf{n}_C = -\nabla \psi_I \times \mathbf{n}_I - \mathbf{H}_{e,I} \times \mathbf{n}_I \quad \text{su } \Gamma$

5. $\mu_I \nabla \psi_I \cdot \mathbf{n}_I = -\mu_C \mathbf{H}_C \cdot \mathbf{n}_C - \mu_I \mathbf{H}_{e,I} \cdot \mathbf{n}_I \quad \text{su } \Gamma$

Formulazione forte

1. $\text{rot}(\sigma^{-1} \text{rot } \mathbf{H}_C) + i\omega\mu_C \mathbf{H}_C = \text{rot}(\sigma^{-1} \mathbf{J}_{e,C}) \quad \text{in } \Omega_C$

2. $\text{div}(\mu_I \nabla \psi_I) = -\text{div}(\mu_I \mathbf{H}_{e,I}) \quad \text{in } \Omega_I$

3. $\psi_I = 0 \quad \text{su } \partial\Omega_I \setminus \Gamma$

4. $\mathbf{H}_C \times \mathbf{n}_C = -\nabla \psi_I \times \mathbf{n}_I - \mathbf{H}_{e,I} \times \mathbf{n}_I \quad \text{su } \Gamma$

5. $\mu_I \nabla \psi_I \cdot \mathbf{n}_I = -\mu_C \mathbf{H}_C \cdot \mathbf{n}_C - \mu_I \mathbf{H}_{e,I} \cdot \mathbf{n}_I \quad \text{su } \Gamma$

Procedura Dirichlet-Neumann

Dato $\lambda_h^0 \in N_{\Gamma,h}$ (spazio discreto della traccia di $N_{C,h}$ su Γ),

per ogni $k \geq 0$ calcolare $\mathbf{H}_{C,h}^k \in N_{C,h}$ tale che per ogni $\mathbf{v}_{C,h} \in N_{C,h}^0 := N_{C,h} \cap H_0(\mathbf{rot}; \Omega_C)$

$$\left\{ \begin{array}{l} \int_{\Omega_C} \left[\sigma^{-1} \mathbf{rot} \mathbf{H}_{C,h}^k \cdot \mathbf{rot} \bar{\mathbf{v}}_{C,h} + i\omega\mu_C \mathbf{H}_{C,h}^k \cdot \bar{\mathbf{v}}_{C,h} \right] = \\ = \int_{\Omega_C} \sigma^{-1} \mathbf{J}_{e,C} \cdot \mathbf{rot} \bar{\mathbf{v}}_{C,h} \\ \mathbf{H}_{C,h}^k \times \mathbf{n}_C = -\lambda_h^k - \mathbf{H}_{e,I,h} \times \mathbf{n}_I \end{array} \right.$$

Procedura Dirichlet-Neumann

quindi calcolare $\psi_{I,h}^k \in V_{I,h}$ tale che per ogni

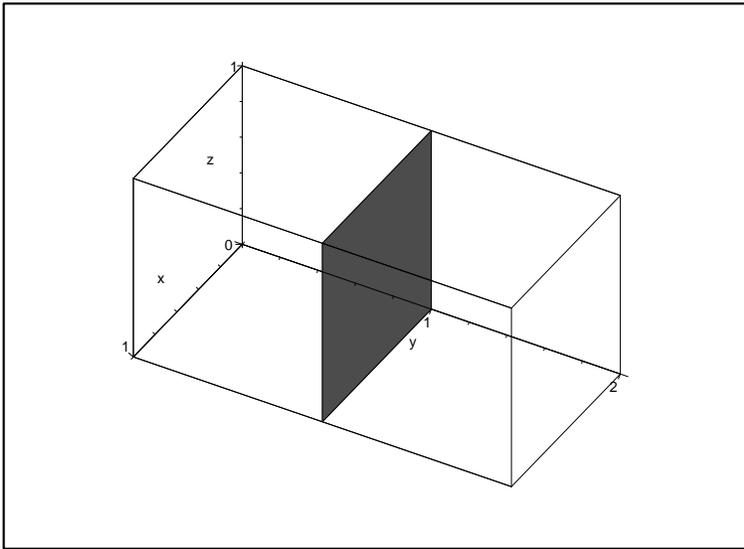
$$\varphi_{I,h} \in V_{I,h}^0 := V_{I,h} \cap H_{0,\partial\Omega}^1(\Omega_I)$$

$$\begin{aligned} & \int_{\Omega_I} \mu_I \nabla \psi_{I,h}^k \cdot \nabla \bar{\varphi}_{I,h} = \\ & = - \int_{\Omega_I} \mu_I \mathbf{H}_{e,I,h} \cdot \nabla \bar{\varphi}_{I,h} - \int_{\Gamma} \mu_C \mathbf{H}_{C,h}^k \cdot \mathbf{n}_C \bar{\varphi}_{I,h} \end{aligned}$$

e aggiornare il dato

$$\boldsymbol{\lambda}_h^{k+1} = (1 - \vartheta) \boldsymbol{\lambda}_h^k + \vartheta (\nabla \psi_{I,h}^k \times \mathbf{n}_I) \quad \text{su } \Gamma$$

Dominio Computazionale



- $\Omega = (0, 1) \times (0, 2) \times (0, 1)$
- $\Omega_C = (0, 1) \times (0, y_\Gamma) \times (0, 1)$
- $\Omega_I = (0, 1) \times (y_\Gamma, 2) \times (0, 1)$
- $\Gamma = \{(x, y_\Gamma, z) \mid x, z \in (0, 1)\}$
- $\mathbf{H}_C \times \mathbf{n}_C = \mathbf{0}$ su $\partial\Omega_C \cap \partial\Omega$

Convergenza

Errore all'iterazione k-esima:

$$\mathbf{\Xi}_C^k = \mathbf{H}_C - \mathbf{H}_C^k$$

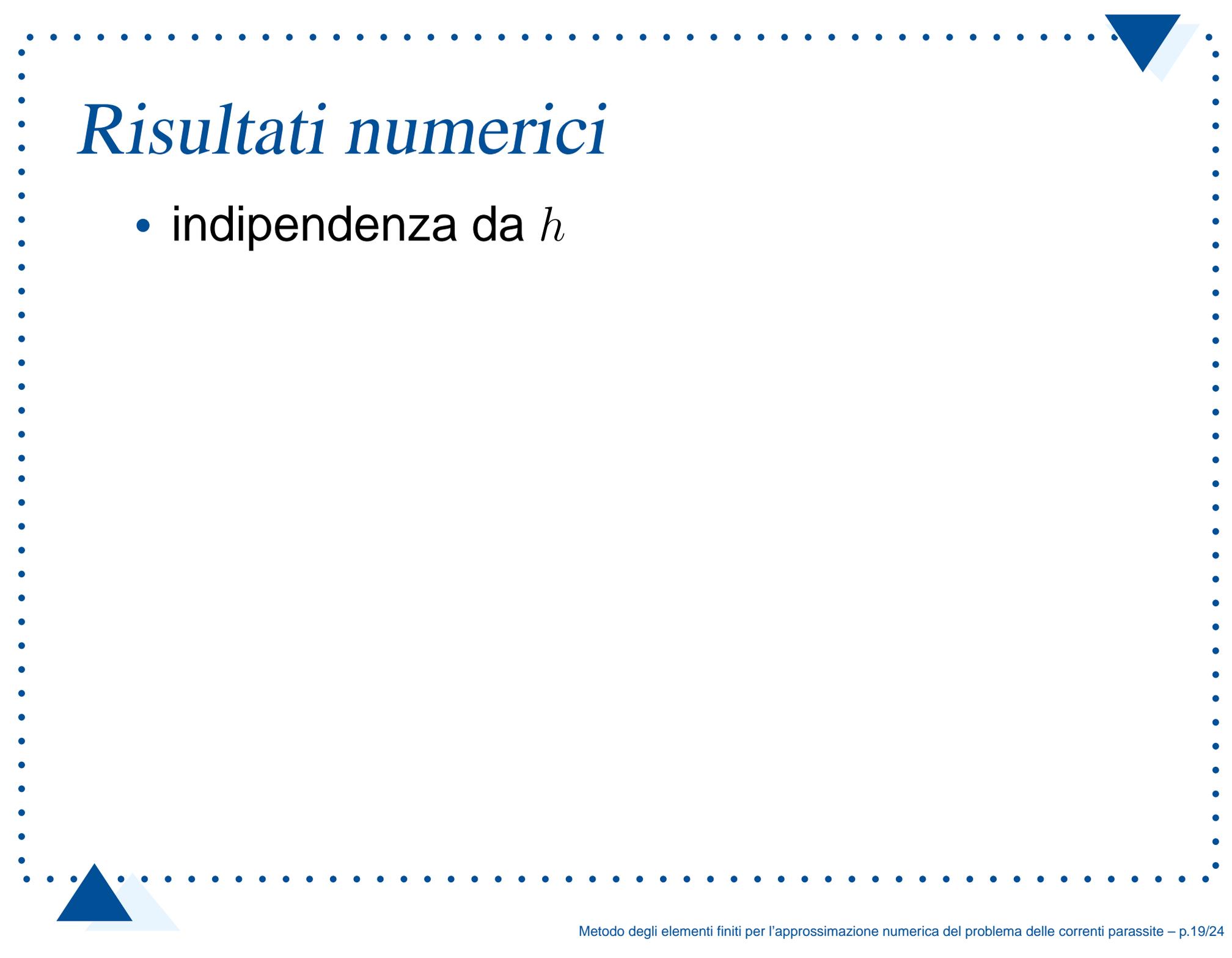
$$\xi_I^k = \psi_I - \psi_I^k$$

$$\left\{ \begin{array}{ll} \mathbf{rot}(\sigma^{-1} \mathbf{rot} \mathbf{\Xi}_C^k) + i\omega\mu_C \mathbf{\Xi}_C^k = \mathbf{0} & \text{in } \Omega_C \\ \mathbf{\Xi}_C^k \times \mathbf{n}_C = \mathbf{0} & \text{su } \partial\Omega_C \\ \mathbf{\Xi}_C^k \times \mathbf{n}_C = -\boldsymbol{\chi}^k & \text{su } \Gamma \end{array} \right.$$

Convergenza

$$\left\{ \begin{array}{ll} -\operatorname{div}(\mu_I \nabla \xi_I^k) = 0 & \text{in } \Omega_I \\ \mu_I \nabla \xi_I^k \cdot \mathbf{n}_I = -\mu_C \Xi_C^k \cdot \mathbf{n}_C & \text{su } \Gamma \\ \xi_I^k = 0 & \text{su } \partial\Omega_I \setminus \Gamma \end{array} \right.$$

$$\chi^{k+1} = (1 - \vartheta) \chi^k + \vartheta (\nabla \xi_I^k \times \mathbf{n}_I) \quad \text{su } \Gamma$$



Risultati numerici

- indipendenza da h



Risultati numerici

- indipendenza da h
- determinazione del parametro di rilassamento ν ottimale



Risultati numerici

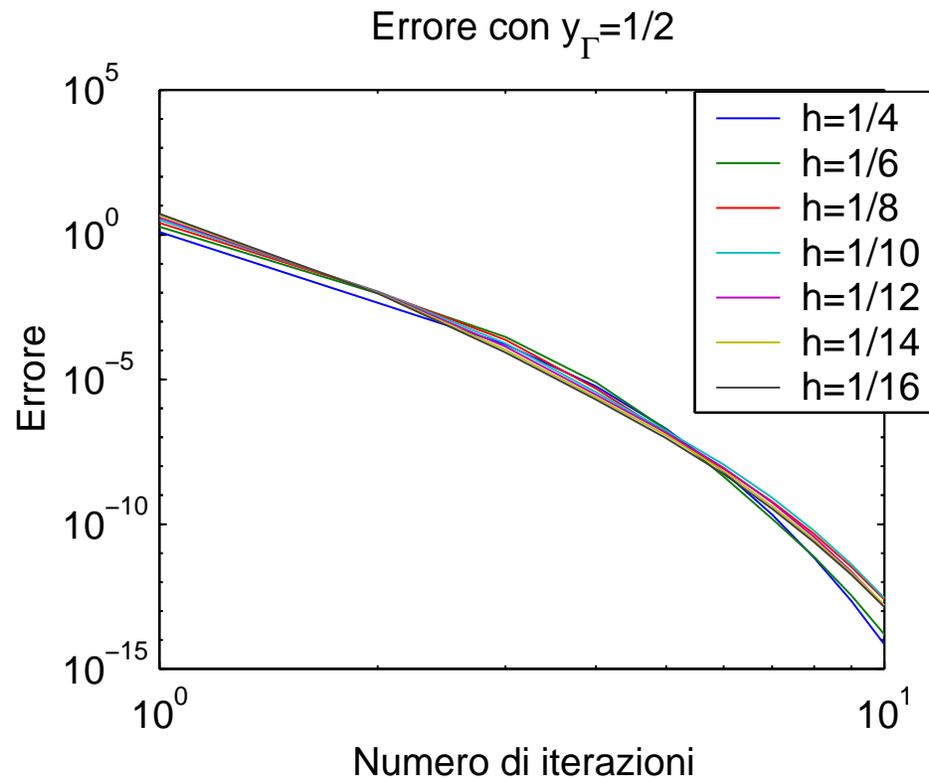
- indipendenza da h
- determinazione del parametro di rilassamento ν ottimale
- robustezza rispetto a y_Γ



Risultati numerici

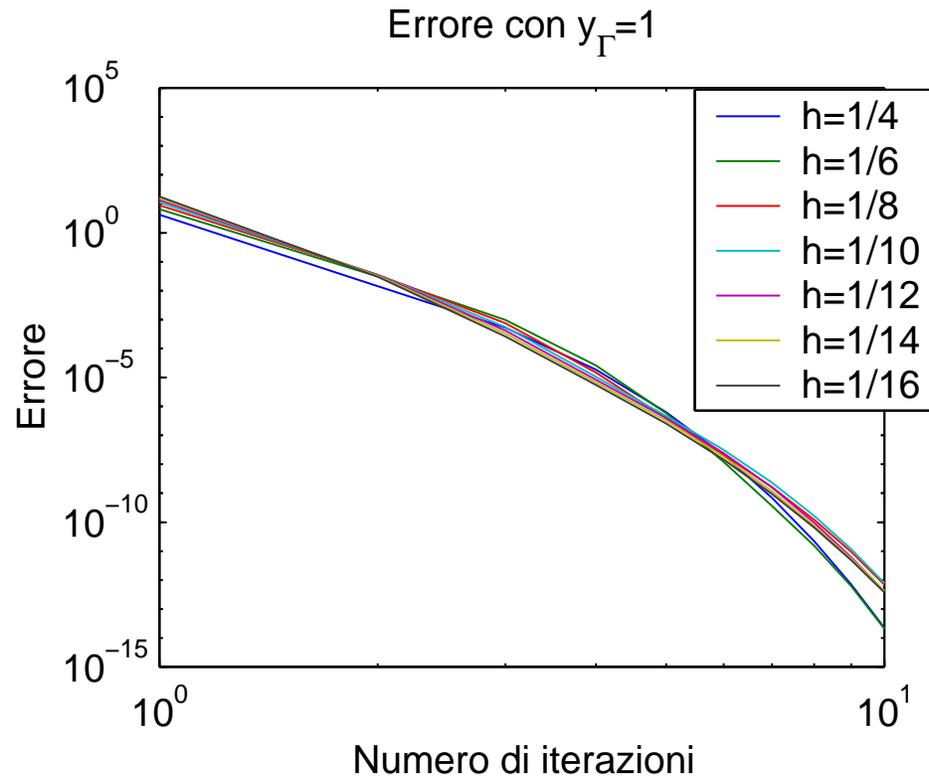
- indipendenza da h
- determinazione del parametro di rilassamento ν ottimale
- robustezza rispetto a y_Γ
- robustezza rispetto ai parametri ω, σ, μ

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{R}^3$



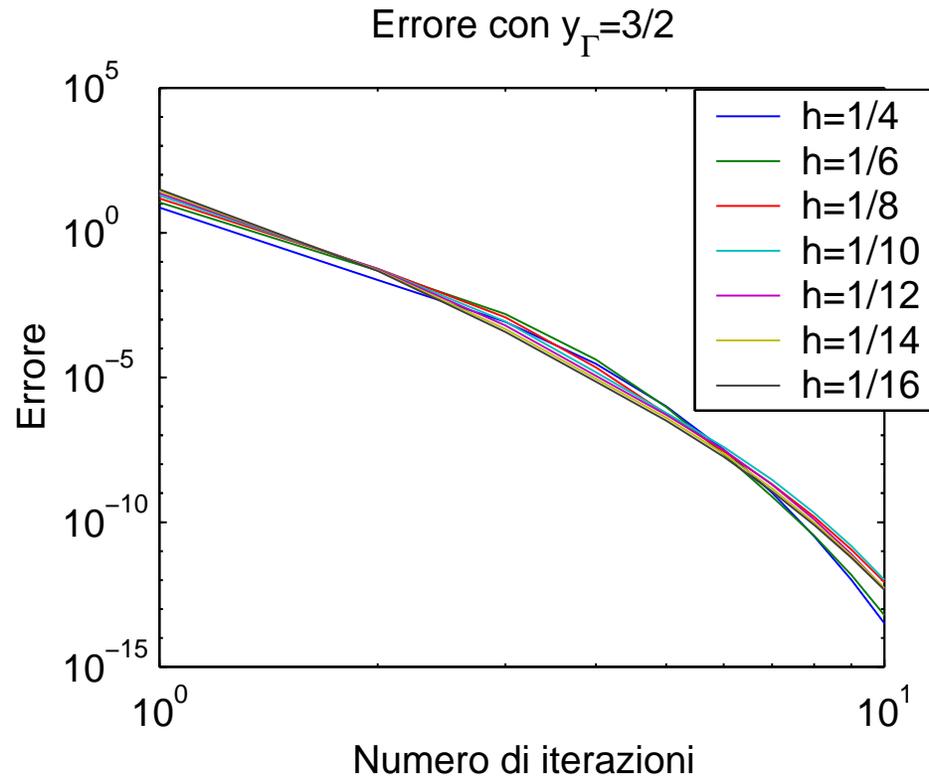
$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{R}^3$



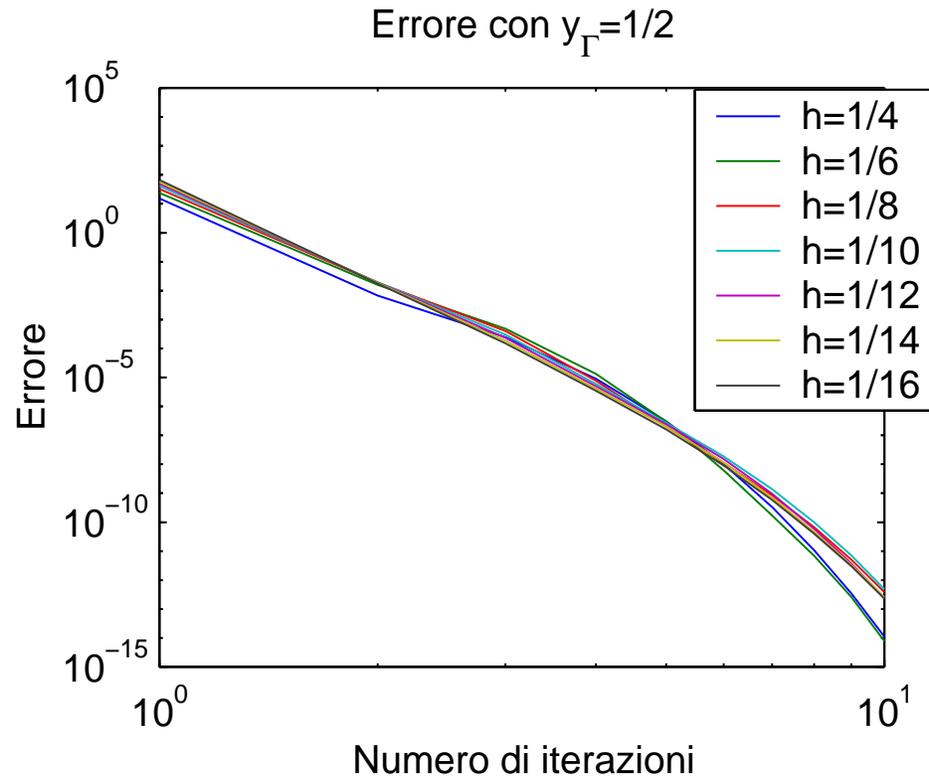
$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{R}^3$



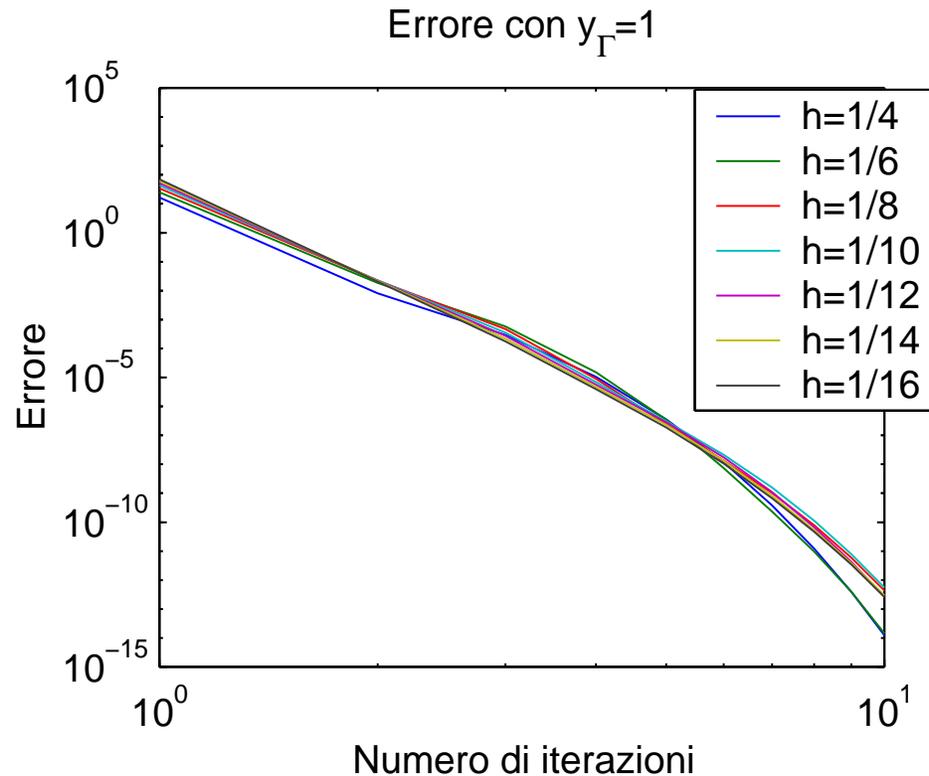
$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{C}^3$



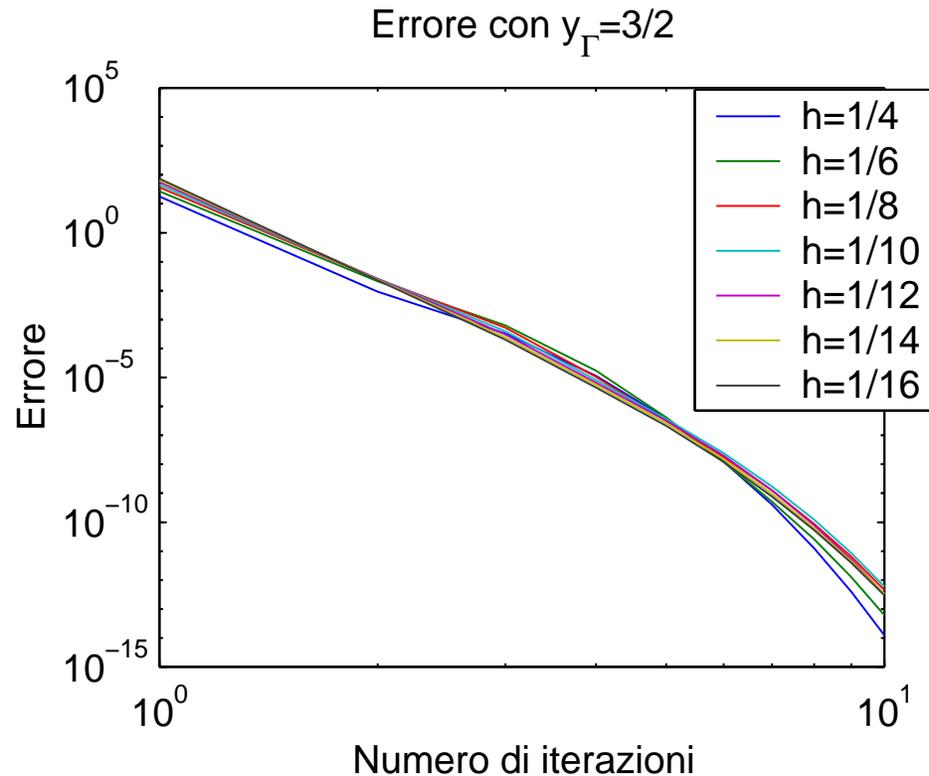
$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{C}^3$



$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

Indipendenza da h , $\lambda : \Gamma \longrightarrow \mathbb{C}^3$

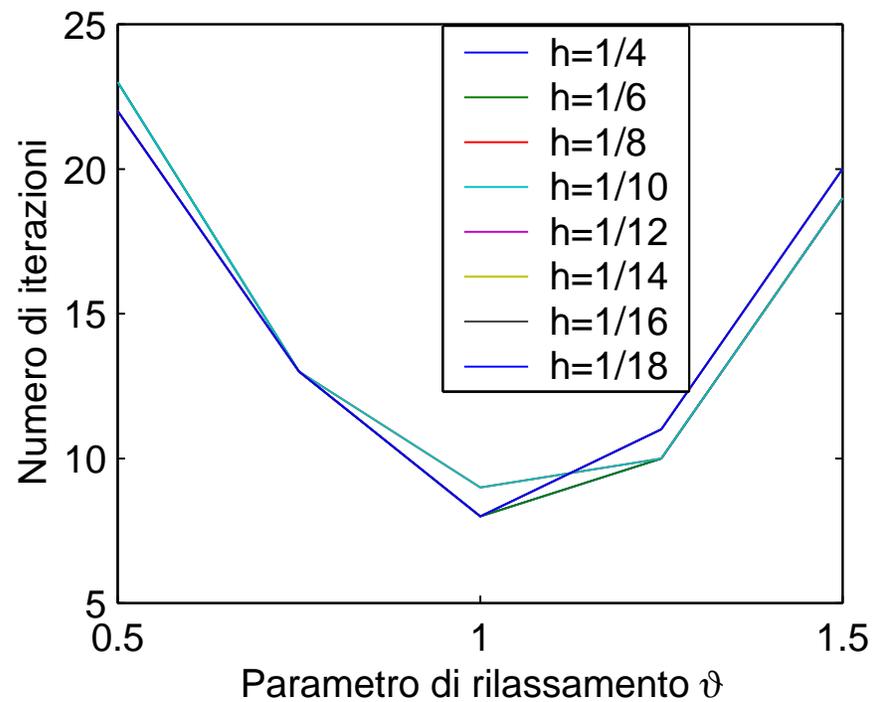


$$\text{Errore} := \|\mathbf{\Xi}_C^k\|_{H(\mathbf{rot}; \Omega_C)}^2 + \|\nabla \xi_I^k\|_{L^2(\Omega_I)}^2$$

ϑ ottimale

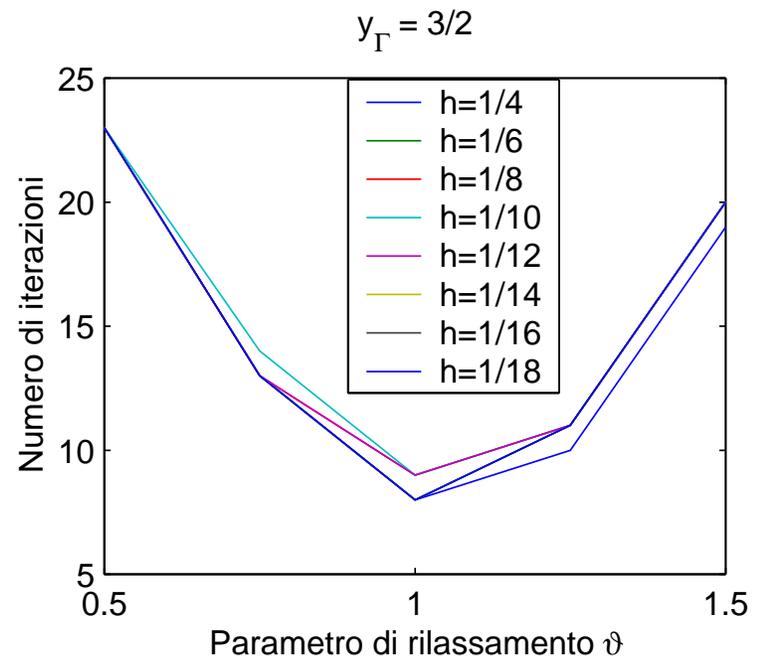
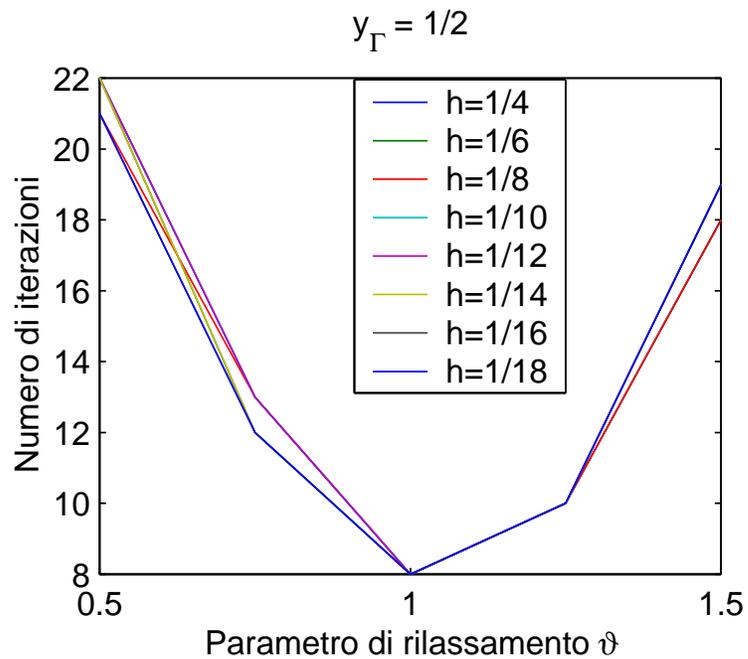
$$\lambda : \Gamma \longrightarrow \mathbb{R}^3$$

$$y_\Gamma = 1$$



ϑ ottimale

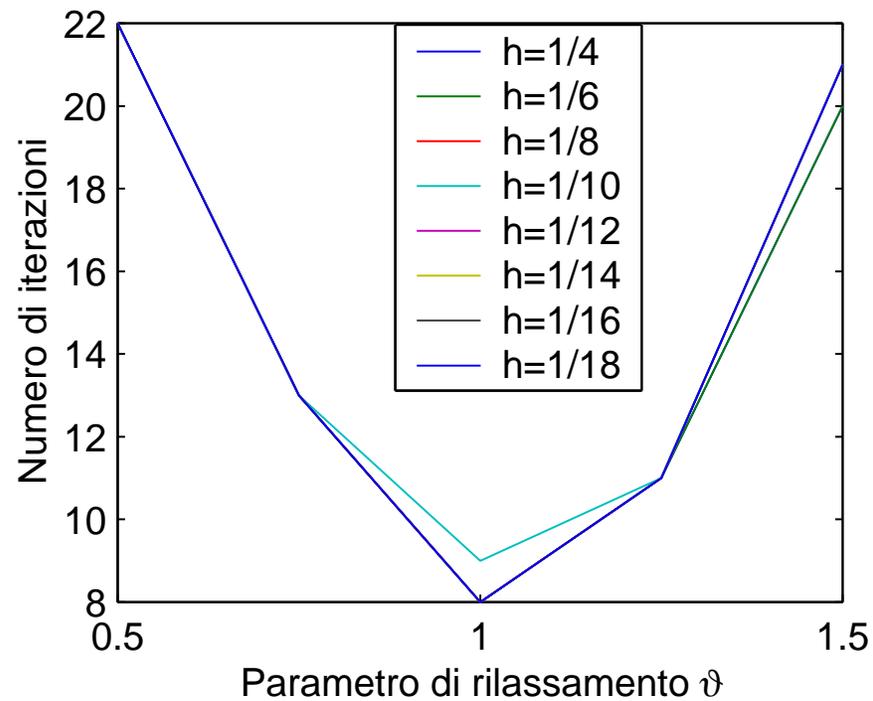
$$\lambda : \Gamma \longrightarrow \mathbb{R}^3$$



ϑ ottimale

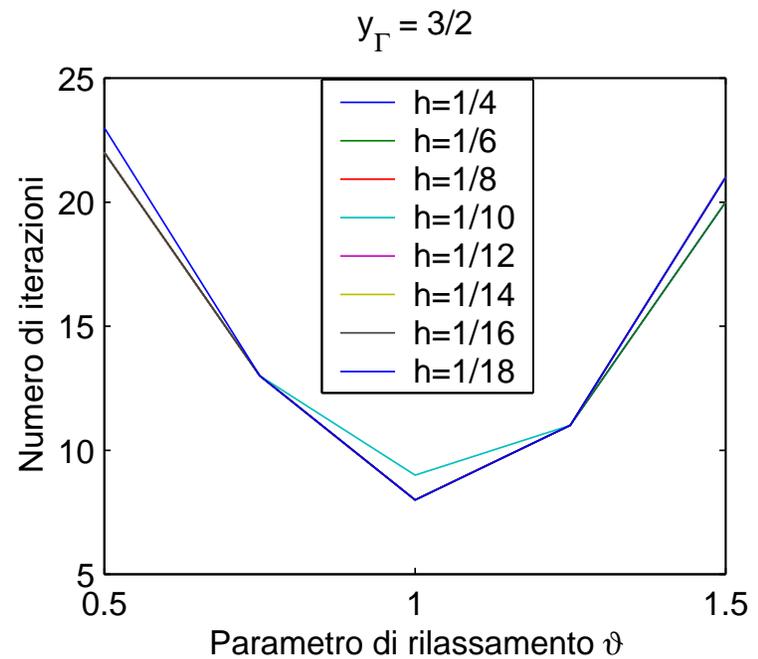
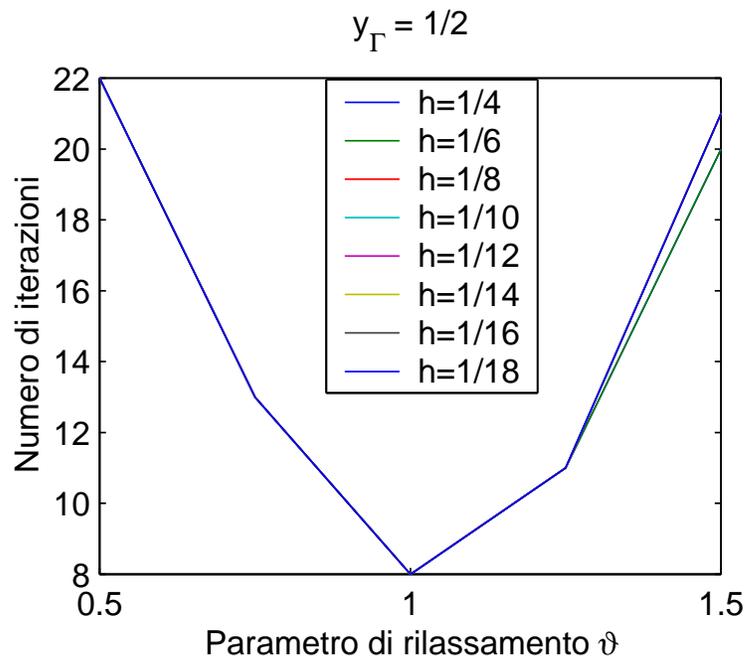
$$\lambda : \Gamma \longrightarrow \mathbb{C}^3$$

$$y_\Gamma = 1$$



ϑ ottimale

$$\lambda : \Gamma \longrightarrow \mathbb{C}^3$$



Robustezza rispetto a $k := \omega \sigma \mu$,

$\lambda : \Gamma \longrightarrow \mathbb{R}^3$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	9	5	4
1/10	14	9	5	4
1/12	14	8	5	4
1/14	15	8	5	4
1/16	15	8	5	3
1/18	14	8	5	4

Robustezza rispetto a $k := \omega \sigma \mu$,

$\lambda : \Gamma \longrightarrow \mathbb{R}^3$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	8	5	3
1/10	13	8	5	3
1/12	14	8	5	3
1/14	14	8	5	3
1/16	14	8	5	3
1/18	14	8	5	3

Robustezza rispetto a $k := \omega \sigma \mu$,

$\lambda : \Gamma \longrightarrow \mathbb{R}^3$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	8	5	4
1/10	14	9	5	4
1/12	15	9	5	4
1/14	15	8	5	4
1/16	15	8	5	4
1/18	14	8	5	4

Robustezza rispetto a $k := \omega \sigma \mu$,

$$\lambda : \Gamma \longrightarrow \mathbb{C}^3$$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	8	5	4
1/10	13	9	5	4
1/12	14	8	5	3
1/14	14	8	5	3
1/16	14	8	5	3
1/18	14	8	5	3

Robustezza rispetto a $k := \omega \sigma \mu$,

$$\lambda : \Gamma \longrightarrow \mathbb{C}^3$$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	8	5	4
1/10	13	8	5	4
1/12	14	8	5	3
1/14	14	8	5	3
1/16	14	8	5	3
1/18	14	8	5	3

Robustezza rispetto a $k := \omega \sigma \mu$,

$$\lambda : \Gamma \longrightarrow \mathbb{C}^3$$

$h \backslash k$	10^{-1}	1	10	10^2
1/6	11	8	5	4
1/8	12	8	5	4
1/10	13	9	5	4
1/12	14	9	5	4
1/14	15	8	5	3
1/16	14	8	5	3
1/18	15	8	5	3